

NOTE:

TABLE SHOWN AT THE CENTER OF TRAVEL
 TO MAINTAIN CATALOG SPECIFICATIONS, THE DS6 MUST BE MOUNTED TO A SURFACE WITH FLATNESS ERROR NOT TO EXCEED 0.013mm/300mm.

THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90°.

TOLERANCES UNL	LESS OTHERWISE SPECIFIED	
X.XX ± .01 X.XXX ± .005 X.XXXX ± .001 FRAC. ± 1/64"	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX CORNER BREAK: .005"020"	FIN
DRAWN BY: KDV	DATE: 12/18/03	MA
ENGINEER: KDV	CHECKED:	1

NISH: ATERIAL:

ECO REV DESCRIPTION

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PRELIMINARY RELEASE

PRODUCTION RELEASE

VARIOUS UPDATES

DONE BY

KDV

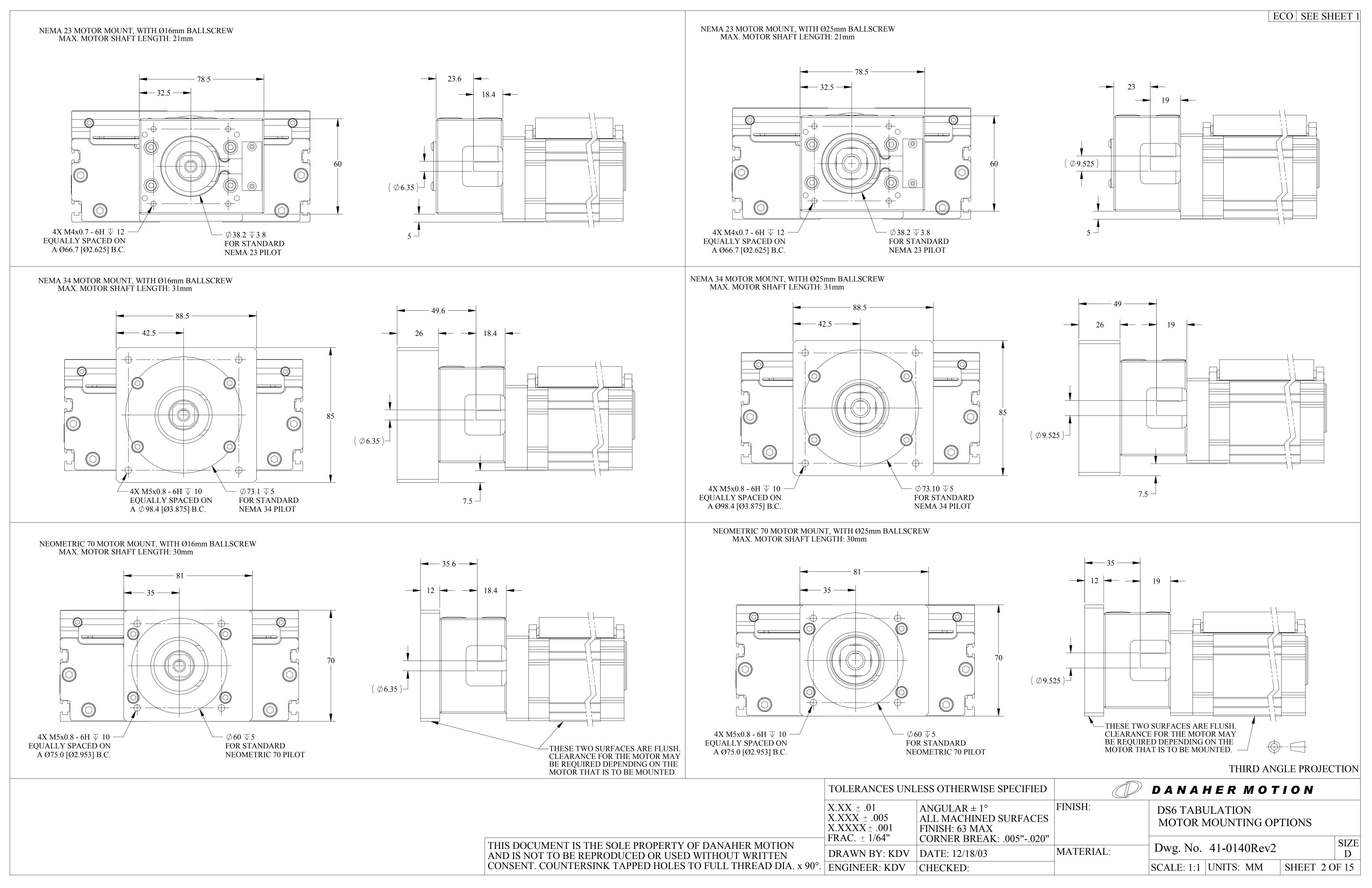
1/13/04

1/20/04 CAE

10/28/04 AMC

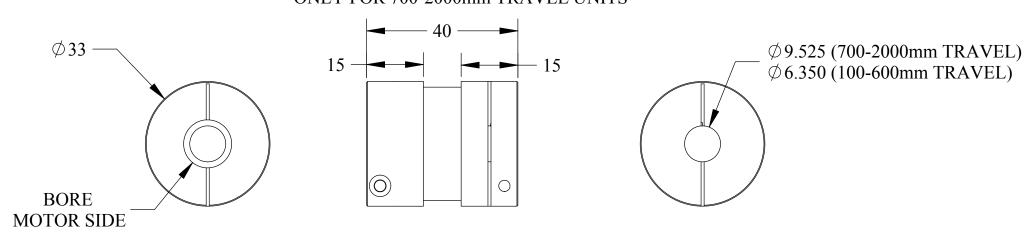
DANAHER MOTION DS6 TABULATION

SIZE Dwg. No. 41-0140Rev2 SHEET 1 OF 15 SCALE: 1:2 UNITS: MM



BELLOWS STYLE MOTOR SIDE BORE SIZES: ENGLISH: 1/4"*, 3/8", 1/2", 5/8", 3/4" METRIC: 11mm*, 14mm, 19mm

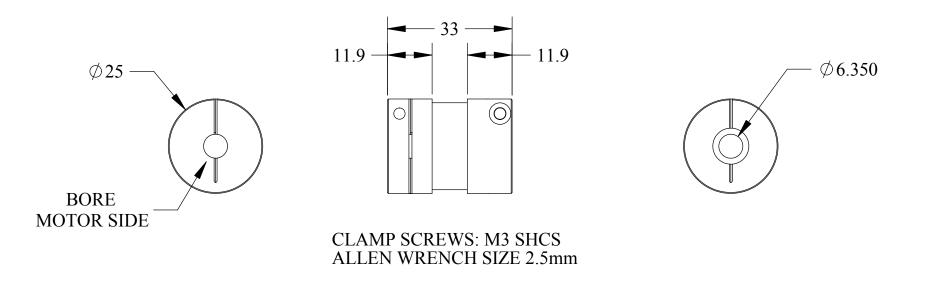
THIS COUPLING USED FOR ALL TRAVELS, EXCEPT * ONLY FOR 700-2000mm TRAVEL UNITS



CLAMP SCREWS: M3 SHCS ALLEN WRENCH SIZE 2.5mm

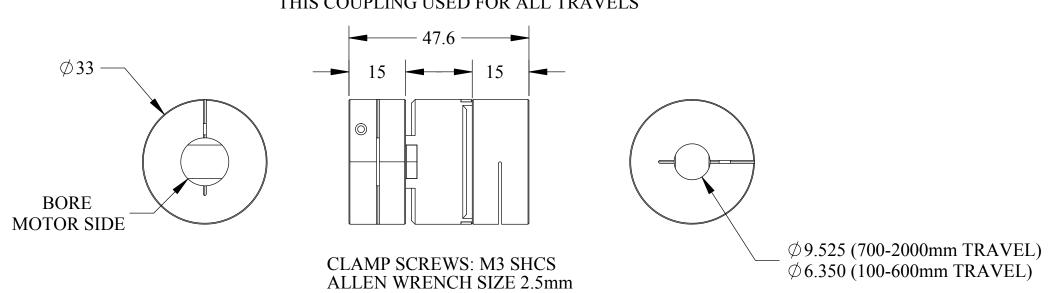
BELLOWS STYLE MOTOR SIDE BORE SIZES: ENGLISH: 1/4" METRIC: 5mm*, 8mm*, 9mm*, 11mm

THIS COUPLING USED ONLY FOR 100-600mm TRAVEL UNITS * THESE BORES AVAILABLE ONLY FOR 100-600mm TRAVEL UNITS



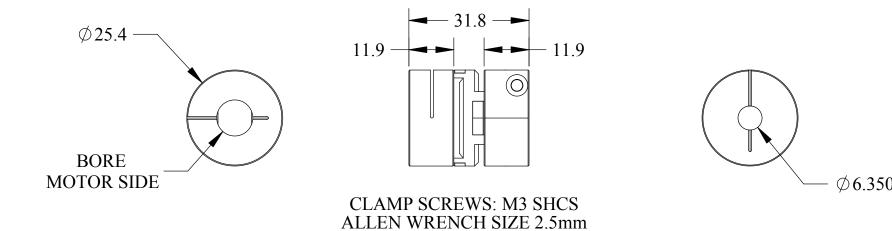
OLDHAM STYLE MOTOR SIDE BORE SIZES: ENGLISH: 1/4", 3/8", 1/2", 5/8", 3/4" METRIC: 11mm, 14mm, 19mm

THIS COUPLING USED FOR ALL TRAVELS

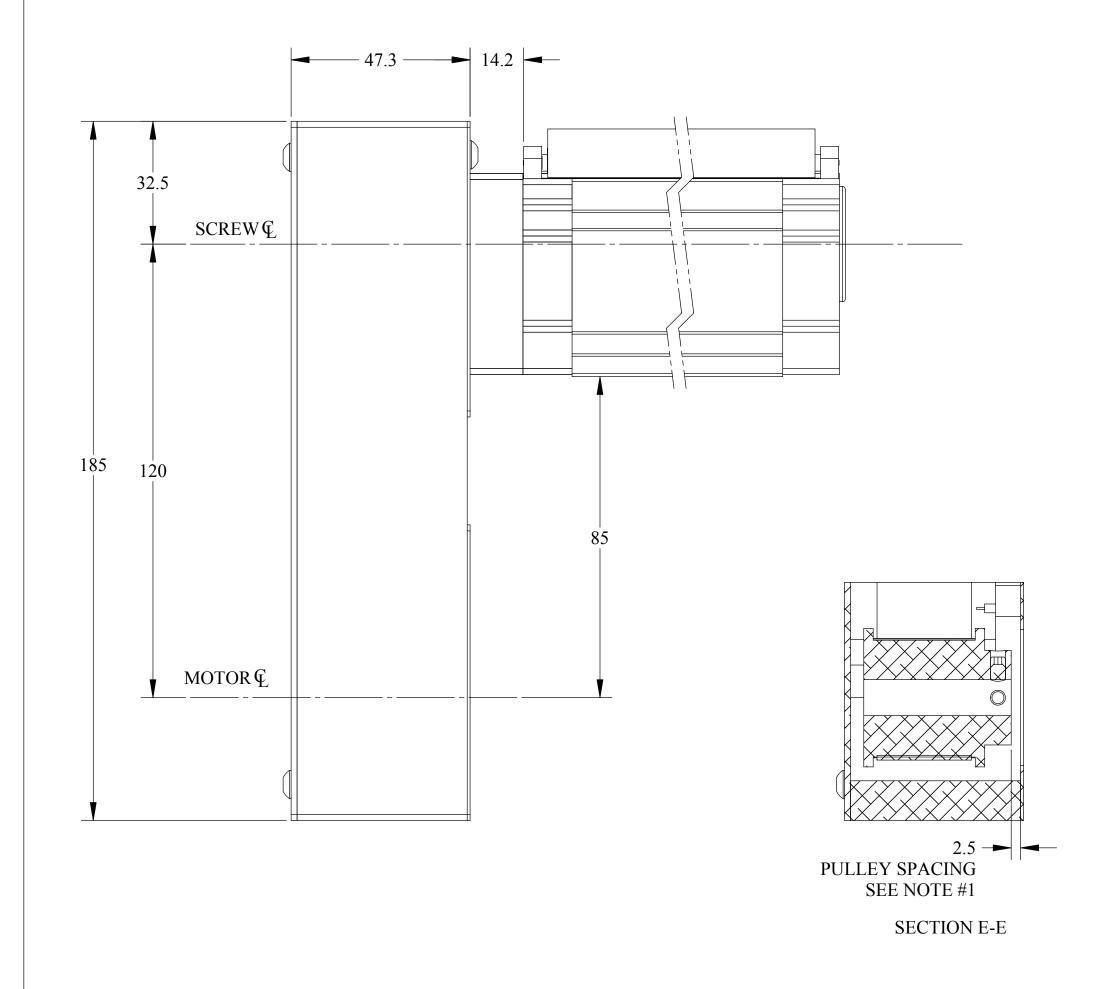


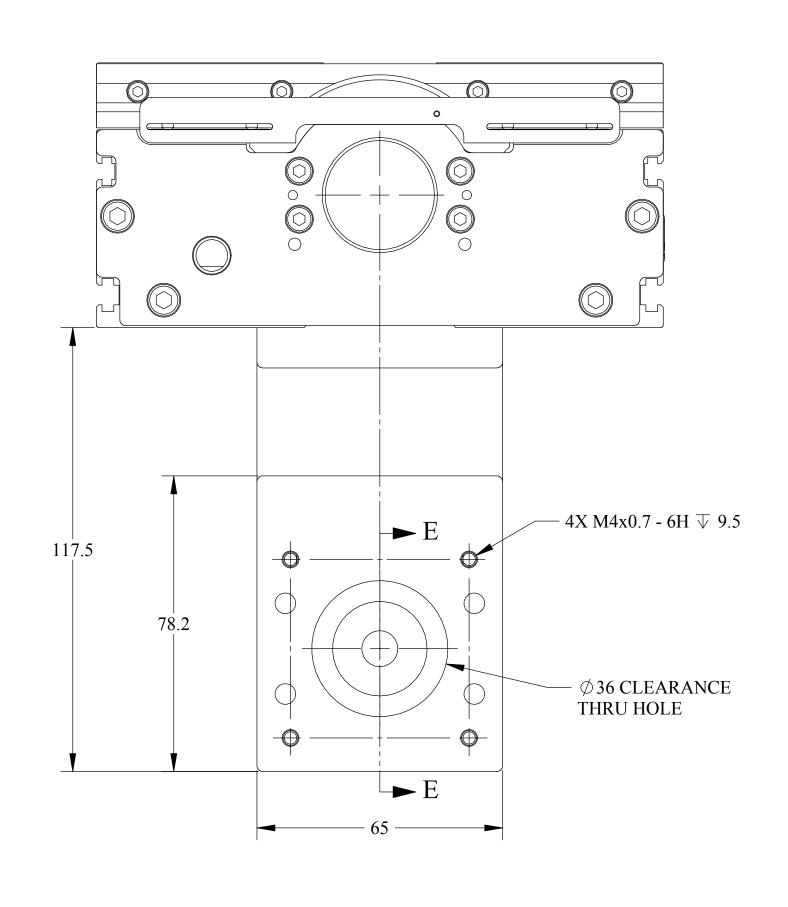
OLDHAM STYLE MOTOR SIDE BORE SIZES: METRIC: 5mm, 8mm, 9mm

THIS COUPLING USED ONLY FOR 100-600mm TRAVEL UNITS THESE BORES ONLY AVAILABLE FOR 100-600mm TRAVEL UNITS



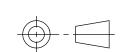
23 FRAME PARALELL UNDER MOUNT



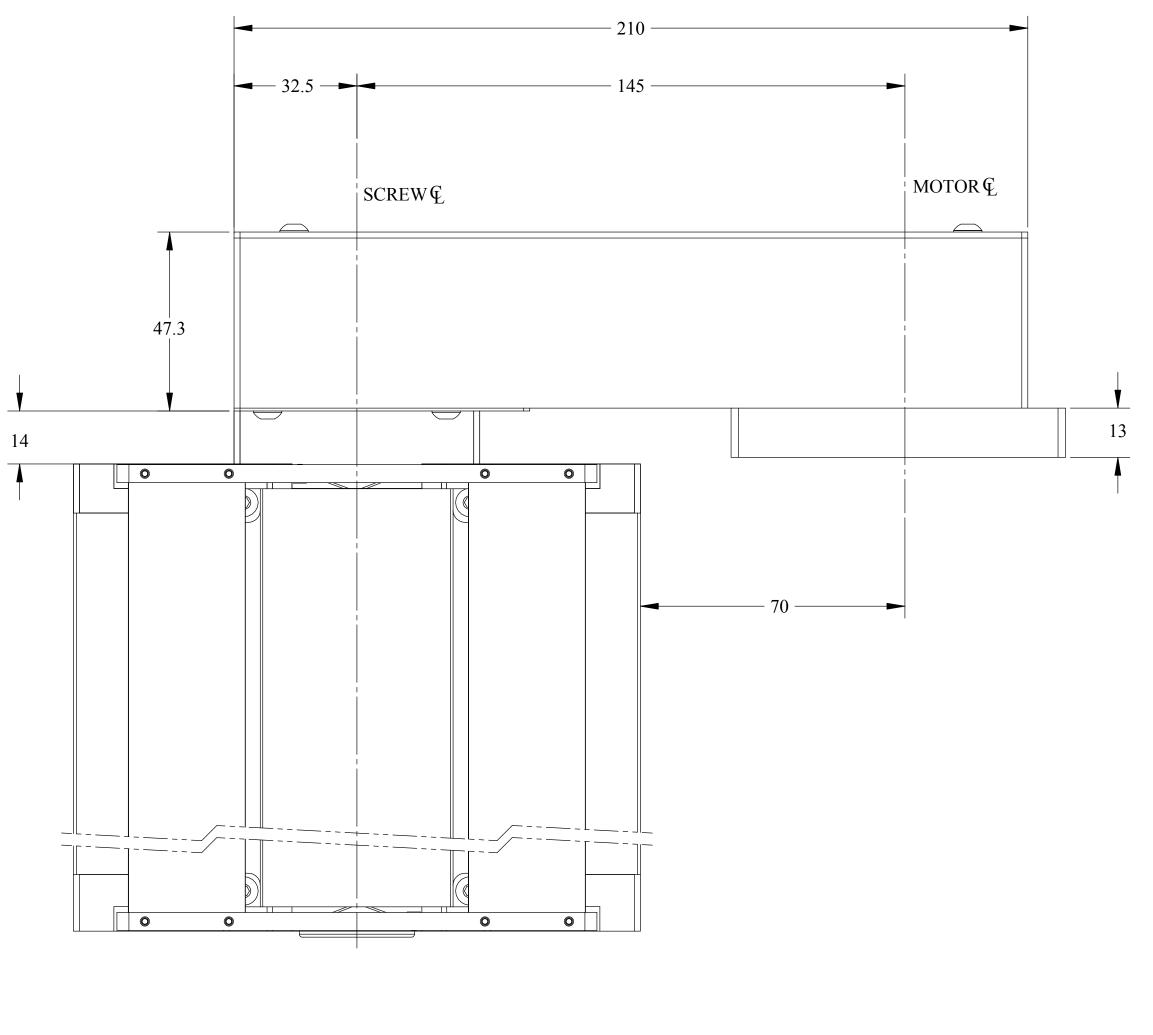


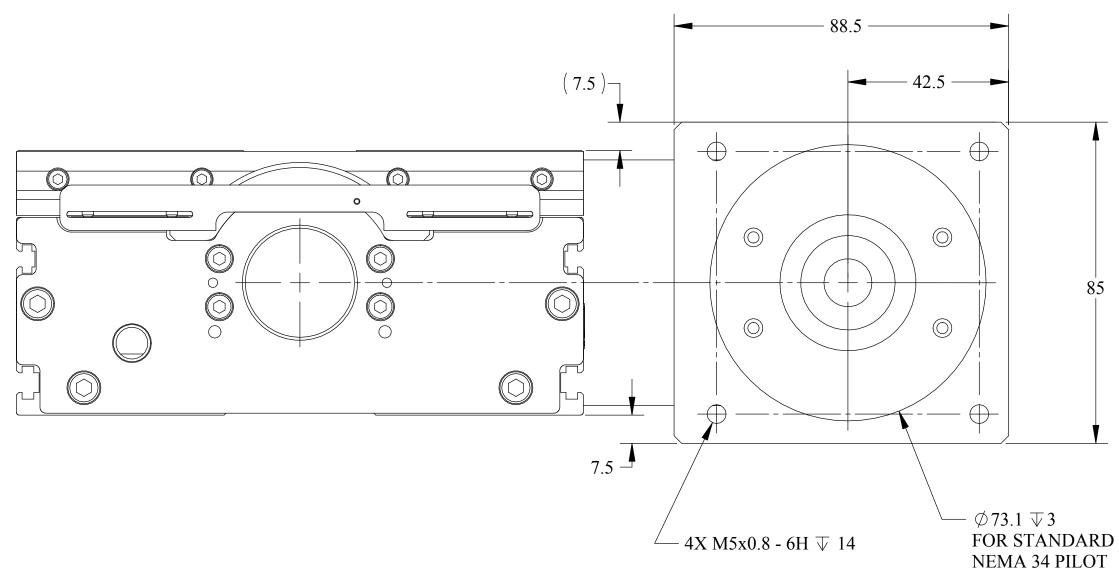
GENERAL NOTES:

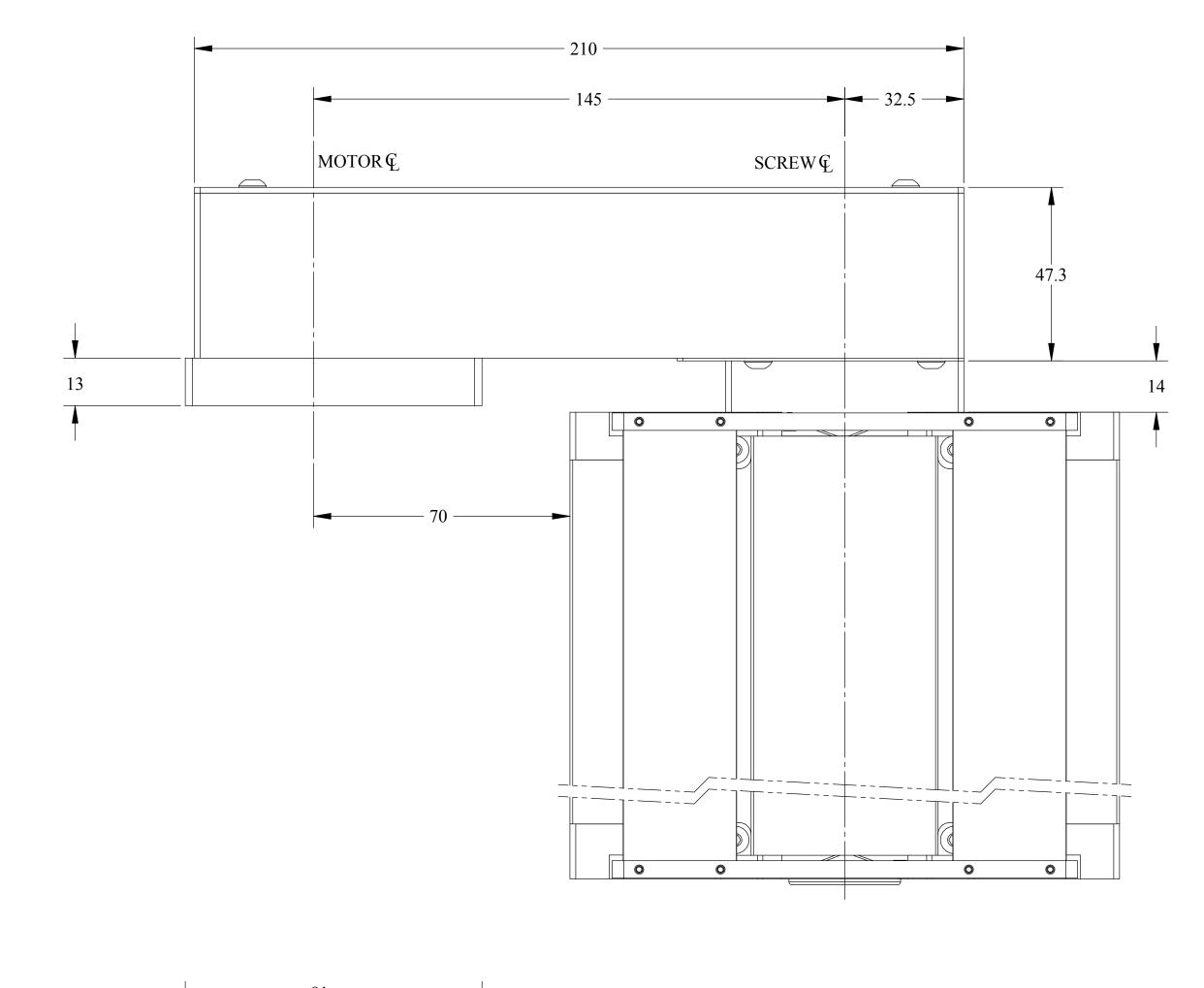
- 1.) PULLEY SPACING SHOWN APPLIES TO BOTH THE MOTOR PULLEY (SHOWN) AND THE DRIVEN PULLEY.
- 2.) ANY OF THE STANDARD MOTOR MOUNTING PLATES CAN BE APPLIED IN ANY OF THE THREE PARALELL MOUNTING CONFIGURATIONS. ALL PLATES MOUNT WITH THE CENTER POINT AT THE SAME POSITION AS THE PLATE SHOWN.

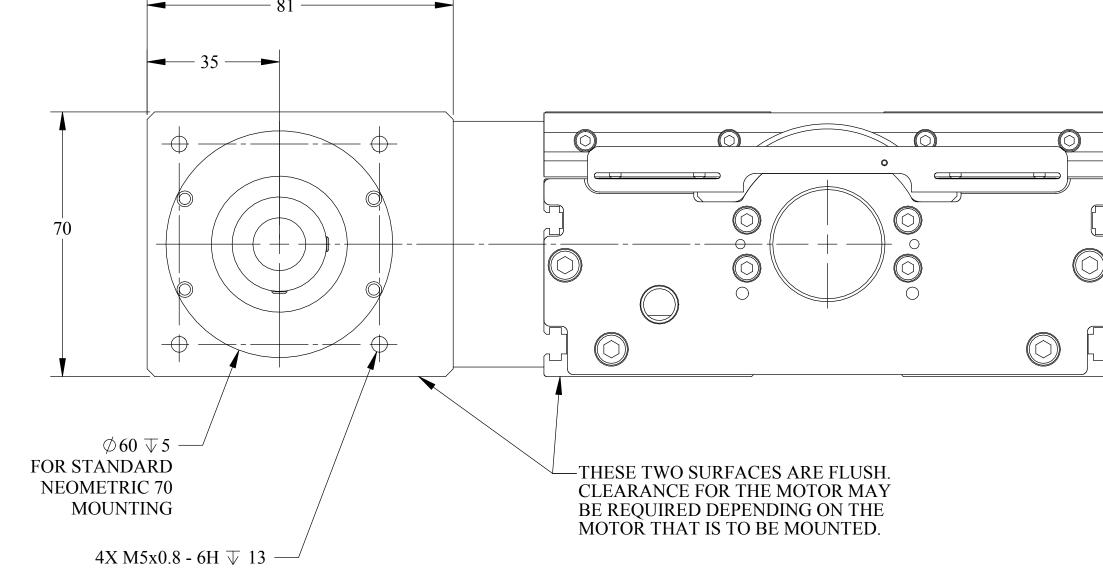


	TOLERANCES UNI	LESS OTHERWISE SPECIFIED		DANAHER MOT	TION
	X.XX ± .01 X.XXX ± .005 X.XXXX ± .001	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX		DS6 TABULATION COUPLINGS AND PARA	ALELL MOUNT
THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN	FRAC. ± 1/64" DRAWN BY: KDV	CORNER BREAK: .005"020" DATE: 12/18/03	MATERIAL:	Dwg. No. 41-0140Rev2	SIZE D
CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90	°. ENGINEER: KDV	CHECKED:		SCALE: 1:1 UNITS: MM	SHEET 3 OF 15









THIRD ANGLE PROJECTION

SIZE

SHEET 4 OF 15

GENERAL NOTES:

PULLEY SPACING SHOWN ON PAGE 3, SECTION E-E, APPLIES TO BOTH THE MOTOR PULLEY AND THE DRIVEN PULLEY, IN ALL INSTANCES.
 ANY OF THE STANDARD MOTOR MOUNTING PLATES CAN BE APPLIED IN ANY OF THE THREE PARALELL MOUNTING CONFIGURATIONS. ALL PLATES MOUNT WITH THE CENTER POINT AT THE SAME POSITION AS THE PLATE SHOWN.

·		TOLERANCES UNI	LESS OTHERWISE SPECIFIED		DANAHER MOTION
		X.XX ± .01 X.XXX ± .005 X.XXXX ± .001	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX		DS6 TABULATION PARALELL MOUNTS
	THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN	FRAC. ± 1/64" DRAWN BY: KDV	CORNER BREAK: .005"020" DATE: 12/18/03	MATERIAL:	Dwg. No. 41-0140Rev2
	CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90°.	ENGINEER: KDV	CHECKED:		SCALE: 1:1 UNITS: MM SHEET 4

IMPORTANT:

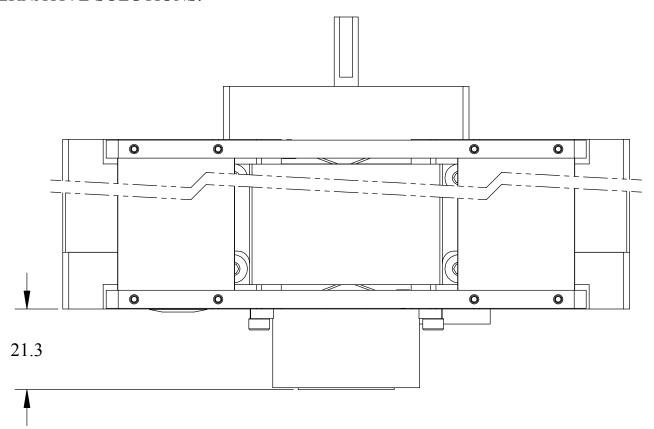
TO REMOVE THE ENCODER:

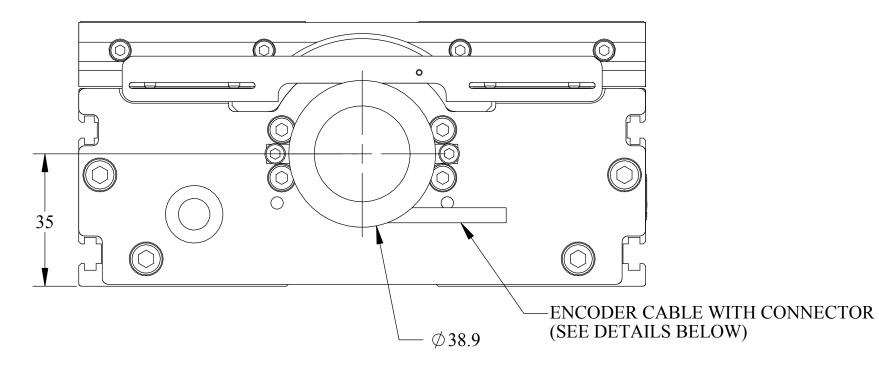
- GENTLY PULL OFF THE ENCODER COVER, - LOOSEN THE TWO M2 MOUNTING SCREWS (BUT DO NOT REMOVE),
- LOOSEN THE SET SCREW IN THE HUB,
- PULL SLIDE/LOCK MECHANISM TO EXTENDED POSITION,
- REMOVE MOUNTING HARDWARE, AND
- SLIDE THE ENCODER OFF THE SCREW SHAFT.

TO RE-INSTALL THE ENCODER:

- SLIDE ENCODER ONTO THE SCREW SHAFT, BY PUSHING ON THE HUB ONLY, UNTIL
- ENCODER IS RESTING ON MOUNTING SURFACE.
- PRESS DOWN ON HUB TO ENSURE IT IS SEATED PROPERLY AND TIGHTEN SET SCREW,
- (SET SCREW SHOULD BE LOCATED OVER THE FLAT ON THE SHAFT)
- INSTALL AND SECURE THE TWO M2 MOUNTING SCREWS,
- PRESS IN THE SLIDE/LOCK MECHANISM COMPLETELY, AND
- SNAP ON THE ENCODER COVER.

NOTE THAT THE ENCODER REFERENCE MARKER POSITION MAY CHANGE SLIGHTLY EACH TIME THIS IS DONE. IF THIS POSITION IS CRITICAL FOR HOMING THE SYSTEM, IT IS RECOMMENDED THAT THE ENCODER NOT BE REMOVED - CONSULT FACTORY FOR ALTERNATIVE SOLUTIONS.





ROTARY ENCODER SPECIFICATIONS Modular Incremental Type Rotary Encoder

Output Format: Square-Wave, Two-Channel quadrature with index. Resolution: 1250 lines/rev (5000ppr post quadrature), one index line. Supply Voltage: 5VDC ±5% Current Requirements: 135mA Output Frequency: 200kHz MAX

MECHANICAL	Pin	Function	Wire Colo
Weight: 57g MAX	1	+VCC	Red
Inertia: 5.16g-cm ²	2	GND	Black
Cover Material: Glass-Filled Polycarbonate	3	CH A	White
Co for initiation of the control of	4	CH A NOT	Yelllow
ENVIRONMENTAL	5	CH B	Green
Operating Temperature: -10 °C to +100 °C	6	CH B NOT	Blue
Storage Temperature: -30 °C to +110 °C	7	INDEX	Orange
Humidity: 90% relative (non-condensing)	8	INDEX NOT	Brown
IP Rating: IP40	-	SHIELD	Drain
Shock: 50 G's for 11ms duration			

Vibration: 5-2000Hz @ 10 G's

Cable Length: 457mm ± 26mm

Cable Type: 8x 28 guage conductors with PVC insulation,
polyester foil shield w/ drain wire,
in PVC cable jacket.

Connector: AMP P/N 103971-7 or equivalent
Mating Connector: Any 0.635mm non-polarized single row header
(2.54mm centers) or may be intalled into single row latching shroud (AMP P/N 103680-5)

POWER-OFF BRAKE OPTION: (-BS)

TO REMOVE THE BRAKE:

- REMOVE THE TWO M4 X 10MM MOUNTING SCREWS,

- PULL THE BRAKE OFF THE DS4.

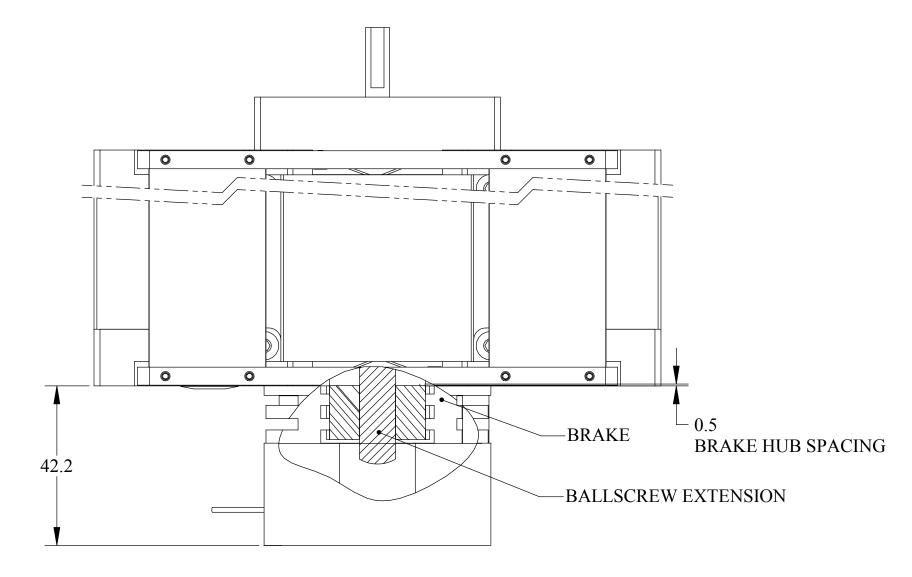
IT IS NOT NECESSARY TO REMOVE THE BRAKE HUB FROM THE BALLSCREW.

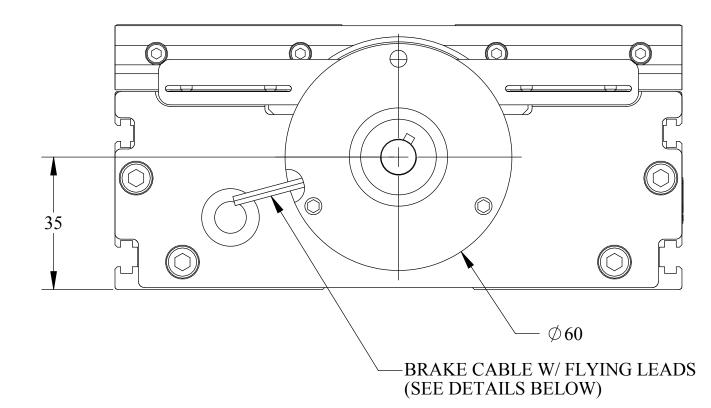
TO RE-INSTALL THE BRAKE:

- PRESS THE BRAKE ONTO THE MOUNTING SURFACE SO THAT THE INTERNAL

TEETH MESH WITH THE TEETH ON THE HUB, - WHEN THE BRAKE IS PROPERLY SEATED, ROTATE TO ALIGN THE MOUNTING

-INSERT AND TIGHTEN THE MOUNTING SCREWS.





BRAKE SPECIFICATIONS Electromagnetic Power-Off Type Brake

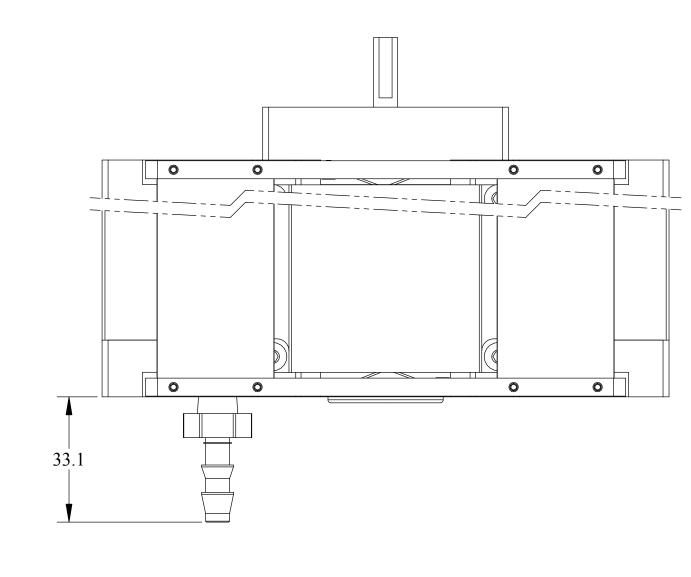
ELECTRICAL Coil Voltage: 24VDC Current Draw: 516mA Resistance: $46.5 \text{ Ohms } \pm 7\% \text{ (nominal)}$ Power: 13W MAX

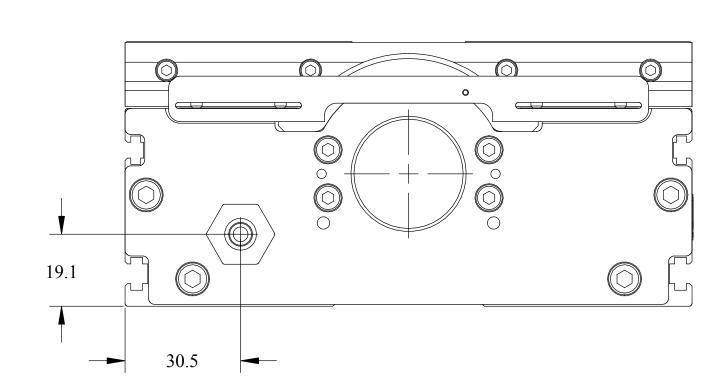
MECHANICAL Holding Torque: 5.65Nm Weight: 520g Inertia: 34.5kg-cm²

Armature Engagement: 120ms Armature Disengagement: 20ms

Max Operating Temperature: 180°C

CABLE Cable Length: 300mm MIN Cable Type: 2x 22 guage conductors with Teflon insulation AIR PURGE FITTING (INCLUDED)



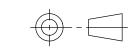


AIR PURGE OPTION Plastic barbed fitting ships with unit.

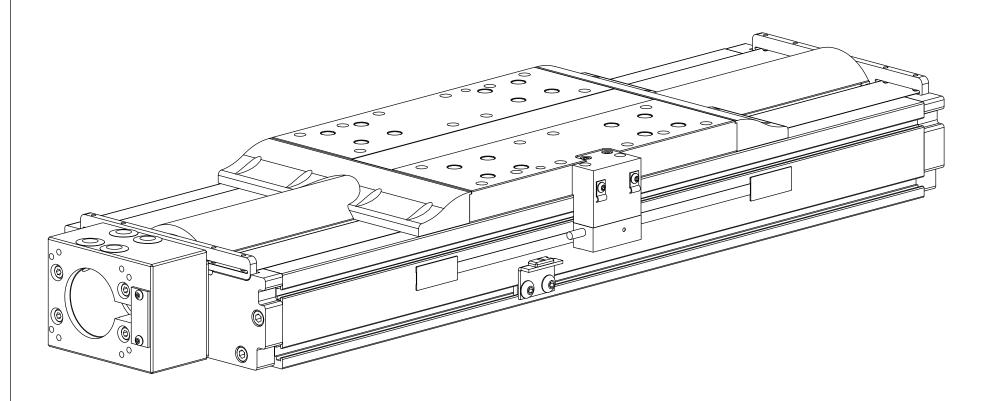
This option can be used to positively pressurize the unit to prevent particulates from entering the unit.

To utilize this option remove black plastic plug, and thread in the included 1/8-NPT barbed fitting. Attach a piece of 1/4" inner diameter plastic tubing (not included) to the barbed fitting and lead out to a CLEAN air source.

Recommended Max Pressure to unit: 14-20kPa (2-3psi)



CABLE Cable Length: 300mm MIN Cable Type: 2x 22 guage conductors with Teflon insulation	TOLERANCES UNLESS OTHERWISE SPECIFIED			DANAHER MOTION		
	X.XX ± .01 X.XXX ± .005 X.XXXX ± .001	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX	FINISH:	DS6 TABULATION ROTARY ENCODER / BRAKE OPTIONS		
THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN	FRAC. ± 1/64" DRAWN BY: KDV	CORNER BREAK: .005"020" DATE: 12/18/03	MATERIAL:	Dwg. No. 41-0140Rev2 SIZE D		
CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90°.	ENGINEER: KDV	CHECKED:	_	SCALE: 1:1 UNITS: MM SHEET 5 OF 15		



LINEAR ENCODER SPECIFICATIONS

Resolution: 0.1μm; 0.5μm; 1.0μm; (Incremental) Signal: Square wave differential line driver; Two chanel quadrature

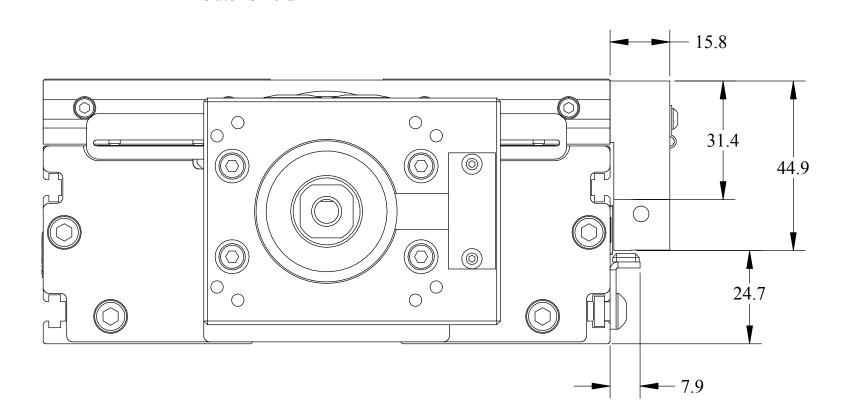
Power Supply: 5VDC ±5%, 120mA (0.5μm and 1.0μm) 150mA (0.1μm only)

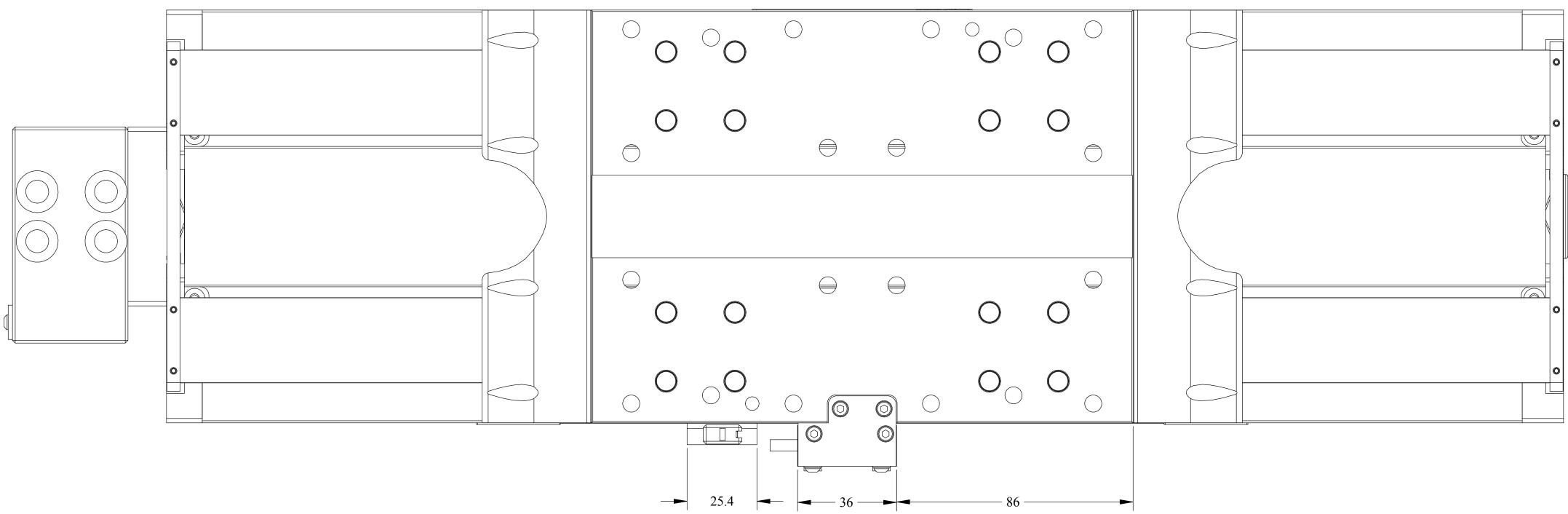
Operating Temperature: 0 °C to +55 °C Storage Temperature: -20 °C to +70 °C Humidity: 10-90% RH (non-condensing) Sealing: IP40 Acceleration: 30g (operating) Shock: 100g for 11ms duration (non-operating) Vibration: 10g @ 55-2000Hz (operating)

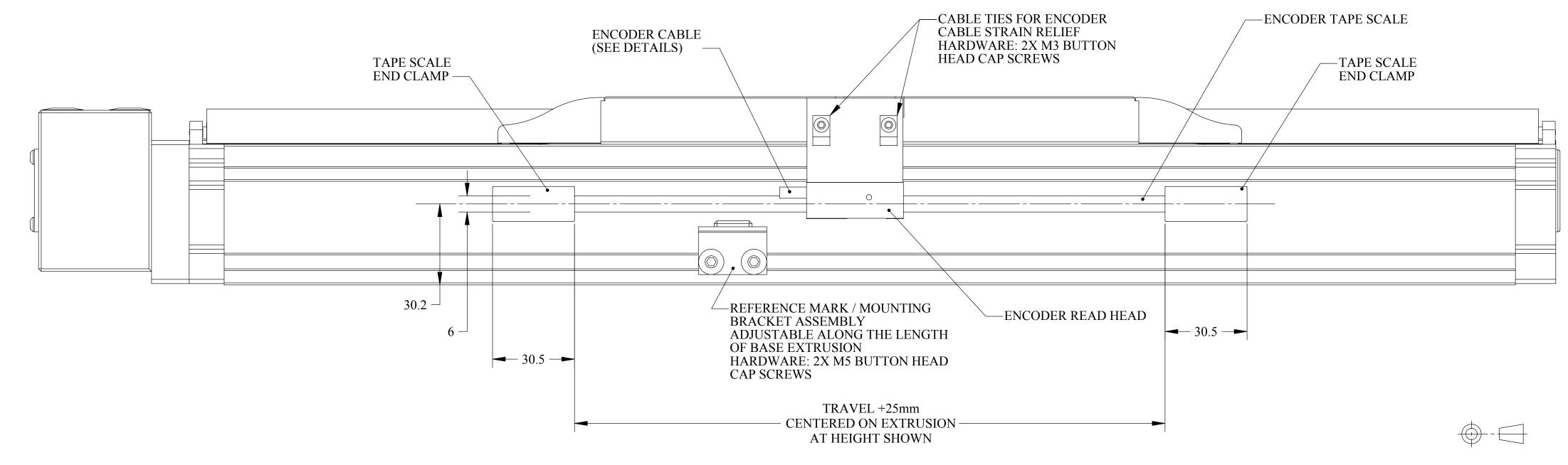
Accuracy: ±3μm/m with linear compensation Linearity: ±1μm/60mm; ±3μm/m

Cable Type: 1.5m ∅4.2mm integral double shielded cable w/ 9-pin 'D' type plug
Cable Flex Life: >20 million cycles at 20mm bend radius

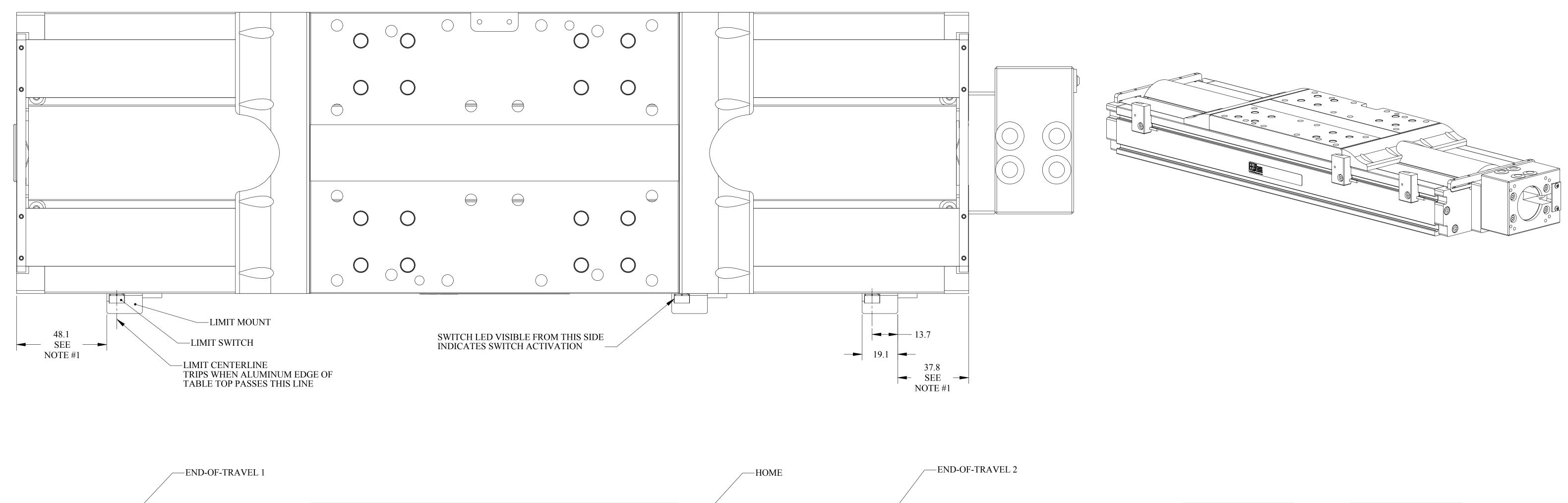
Pin Function
1 0VDC White
2 CH A Green
3 CH Z Pink
4 CH B Blue
5 +5VDC Brown
6 CH A NOT Yellow
7 CH Z NOT Grey
8 CH B NOT Red
9 Inner Shield
- Outer Shield -----

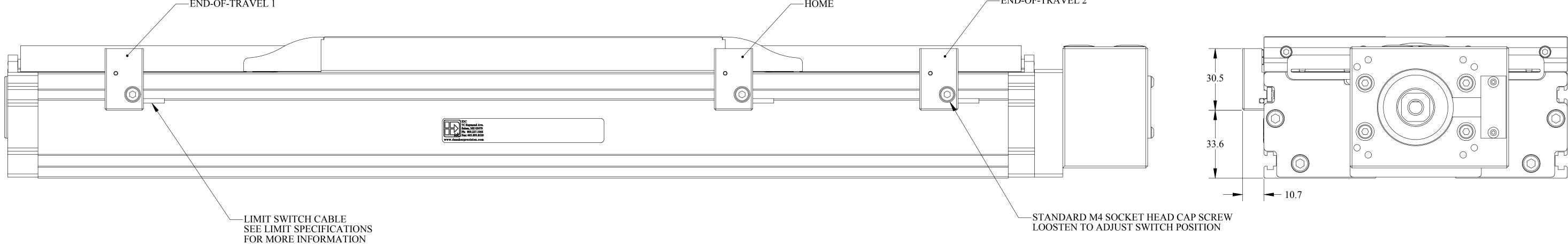






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	X.XX ± .01 X.XXX ± .005 X.XXXX ± .001 FRAC. ± 1/64"	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX CORNER BREAK: .005"020"	FINISH:	DS6 TABULATION LINEAR ENCODER OPTION	
THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN			MATERIAL:	Dwg. No. 41-0140Rev2	SIZE D
	ENGINEER: KDV	CHECKED:		SCALE: 1:1 UNITS: MM	SHEET 6 OF 15





LIMIT SWITCH SPECIFICATIONS: **Inductive Proximity Sensors**

Available Types: NPN Normally Open / Closed PNP Normally Open / Closed

Repeatibility: ±8μm

Power Supply: 5 to 30 VDC Current Consumption: ≤10ma Current Capacity: 100ma

Temperature Range: -20°C to +70°C Sealing: IP67

Cable: 5m Cable w/ 3 x 28AWG conductors and flying leads

WIRING COLORS +VDC Brown
Ground Blue
Signal Black

NOTES:

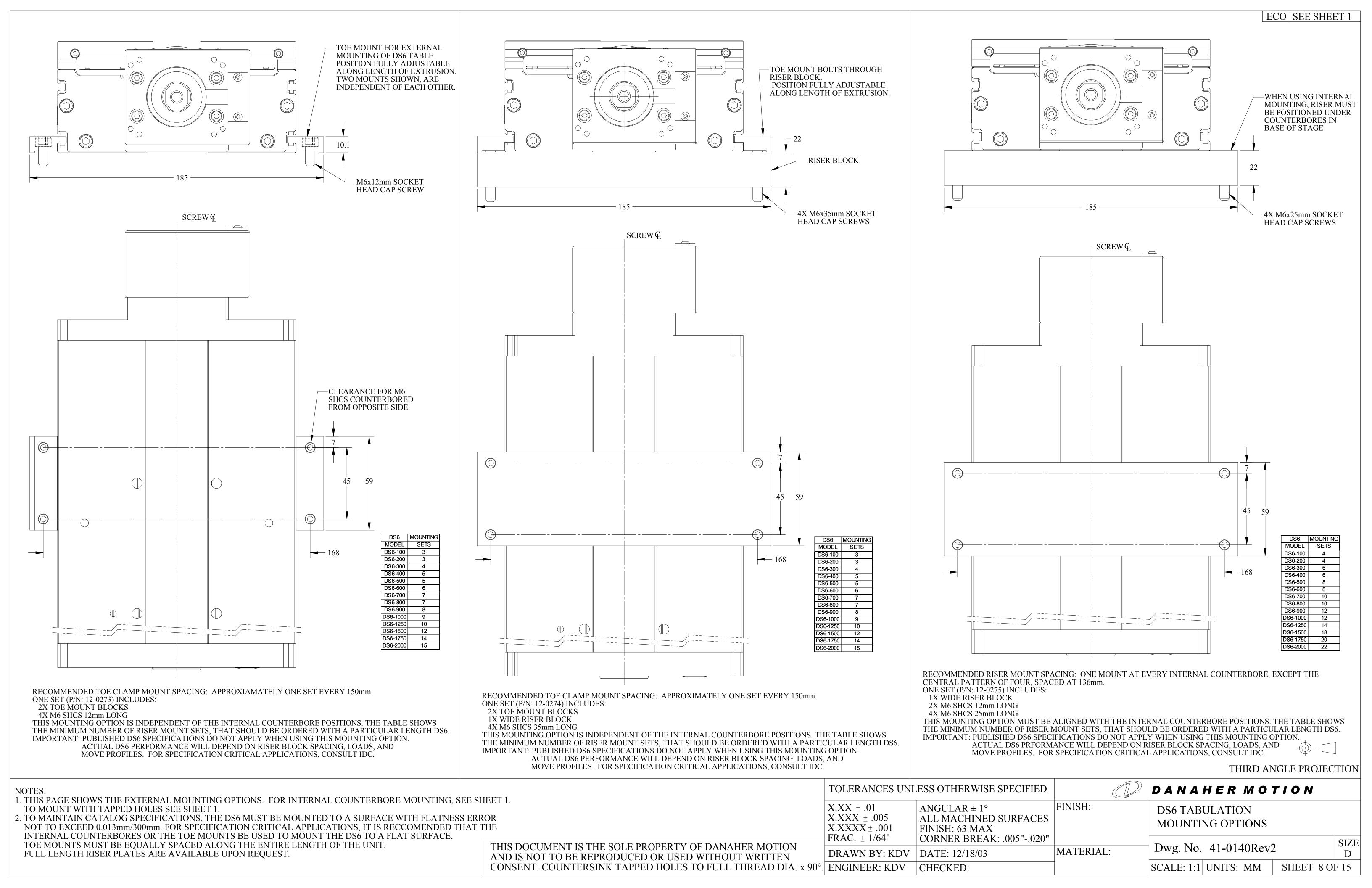
1. MINIMUM DISTANCE FROM END OF TABLE TO LIMIT SWITCH MOUNT TO ENSURE

LIMIT TRIPS PRIOR TO TABLE HARD STOP BEING REACHED.

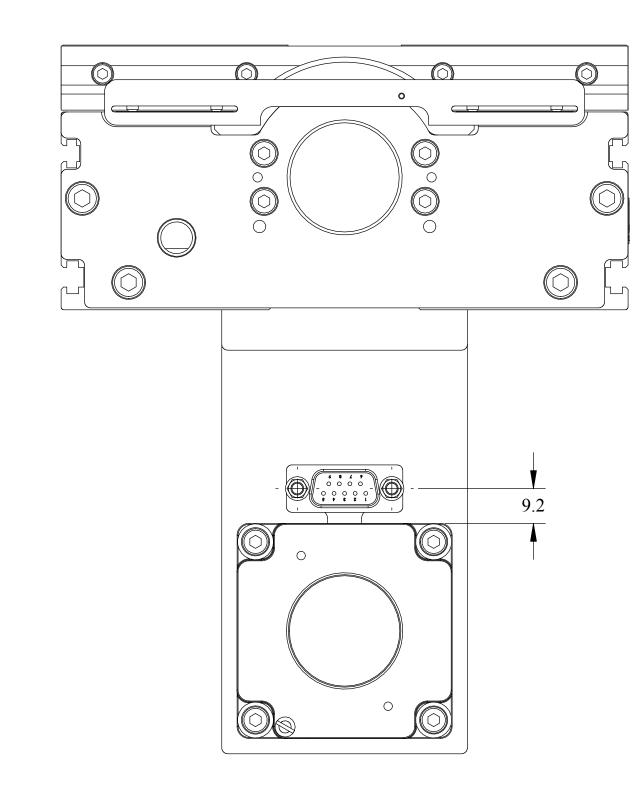
2. ALL SWITCH ASSEMBLIES ARE FULLY ADJUSTABLE ALONG THE LENGTH OF THE BASE EXTRUSION. TO ADJUST POSITION, SLIGHTLY LOOSEN M4 SCREW, MOVE SWITCH TO DESIRED LOCATION, AND RE-TIGHTEN SCREW.

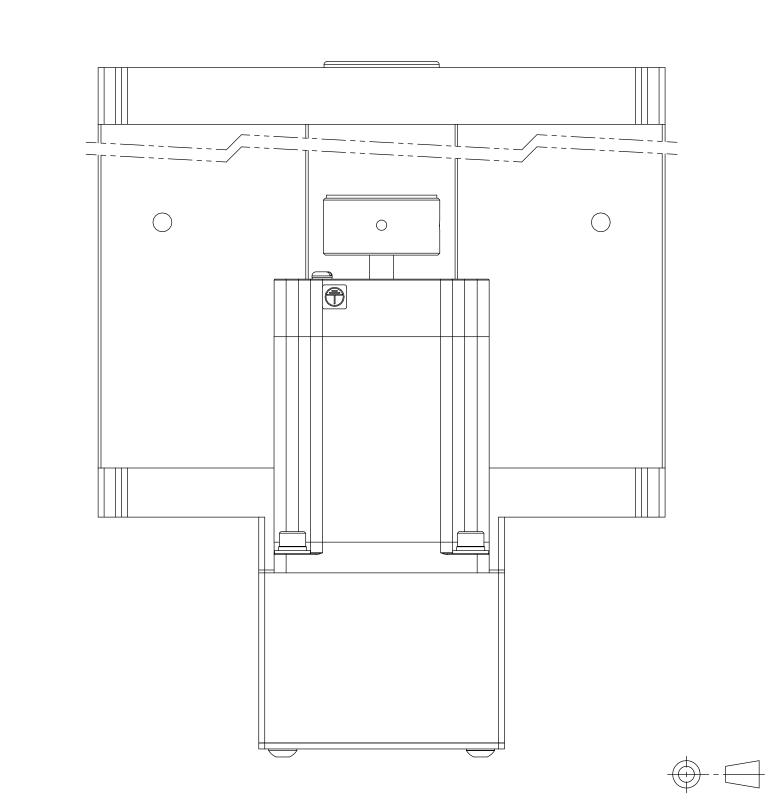
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	FRAC. ± 1/64" DRAWN BY: KDV	CORNER BREAK: .005"020" DATE: 12/18/03	MATERIAL:	Dwg. No.	41-0140Rev2		SIZE D
)°.	ENGINEER: KDV	CHECKED:		SCALE: 1:1	UNITS: MM	SHEET 7 OI	F 15

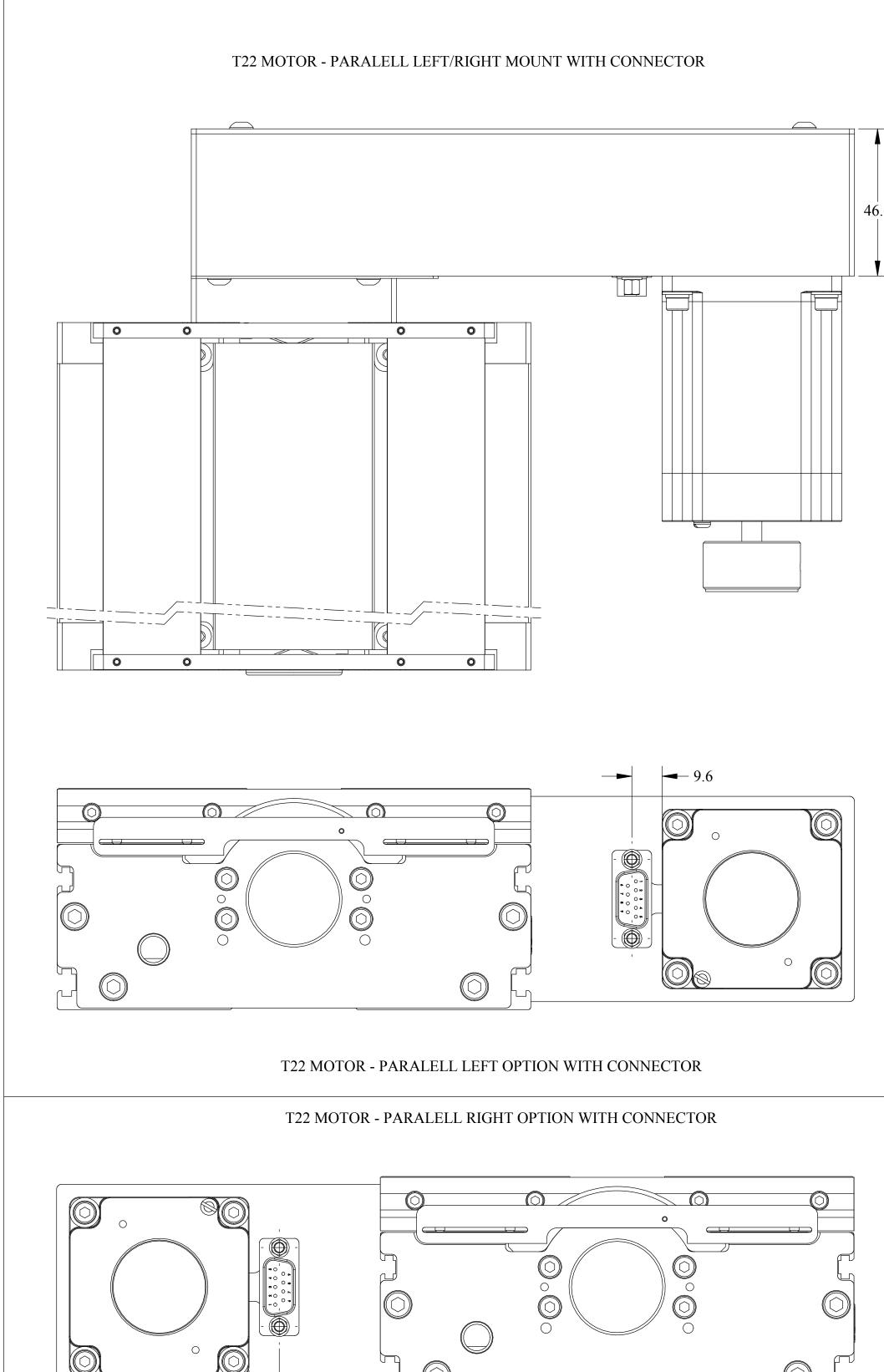








THIRD ANGLE PROJECTION



ORANGE A-WHITE GREEN BLUE BLACK VIOLET YELLOW

MOTOR CONNECTOR | STEPPER | MATING CABLE

WIRE COLOR

#4-40 GROUND SCREW—

MOTOR RADAMETERS	1	1
MOTOR PARAMETERS	TOOT (Corios)	T22\/ (Darallal)
	T22T (Series)	T22V (Parallel)
Cont. Stall Torque	1.40 N-m	[200 oz-in]
Rated Cont. Current / Phase	0.90A	1.80A
Phase Inductance (±20%)	64mH	16mH
Weight	1.23 kg	[2.70lb]
Potor Inortia	$0.0409 \times 10^{-3} \text{ kg m}^2$	2 [0056 oz in soc 2]

-STD 9-PIN D-SHELL CONNECTOR (PLUG)

BROWN $0.0408 \times 10^{-3} \text{ kg-m}^2 [.0056 \text{ oz-in-sec}^2]$ Rotor Inertia METAL HOOD SHIELD

 \emptyset 30.8

— 56.9□ —

78.5

T22 MOTOR - INLINE MOUNT WITH CONNECTOR

0

NOTE:

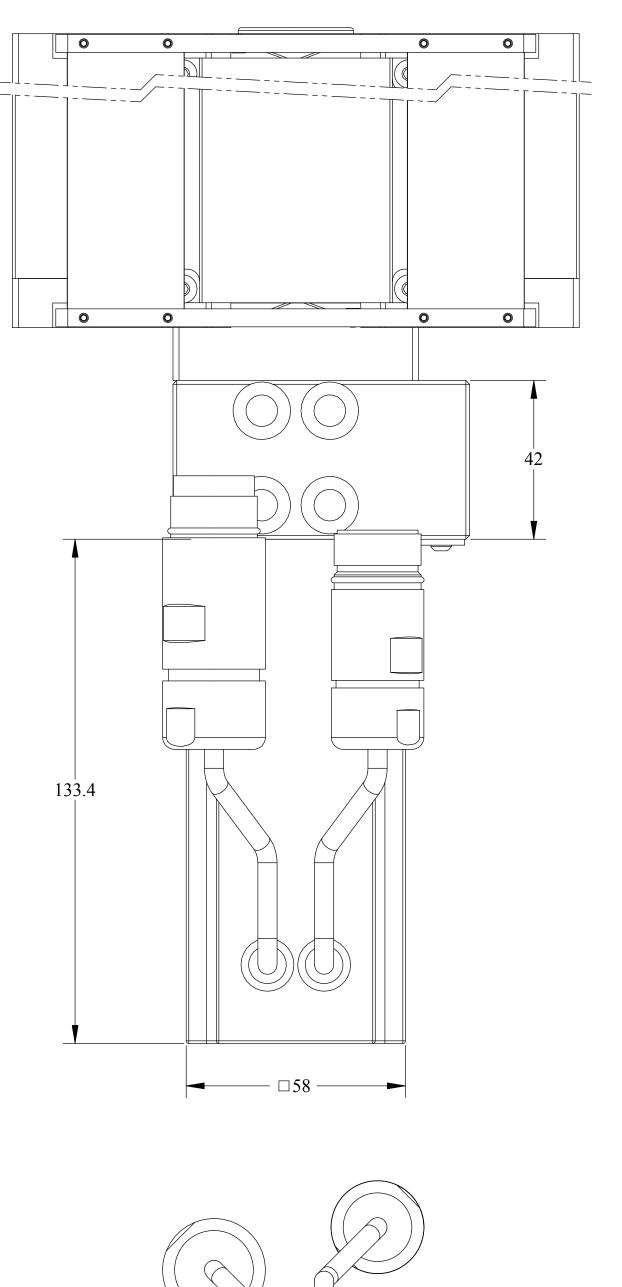
PIN#

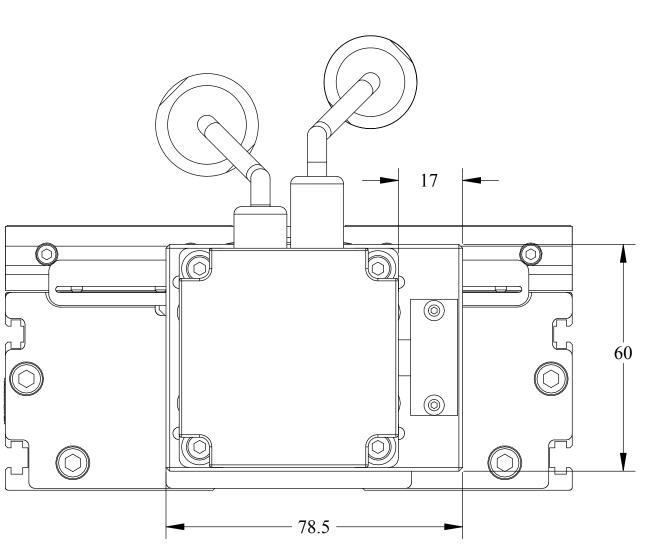
- 1.) BASIC MOTOR DIMENSIONS AND CONNECTOR LOCATIONS SHOWN. REFER TO SHEET 2 AND 3 FOR MORE DETAILS
- 2.) 3 METER CABLE SUPPLIED WITH MATING CONNECTOR

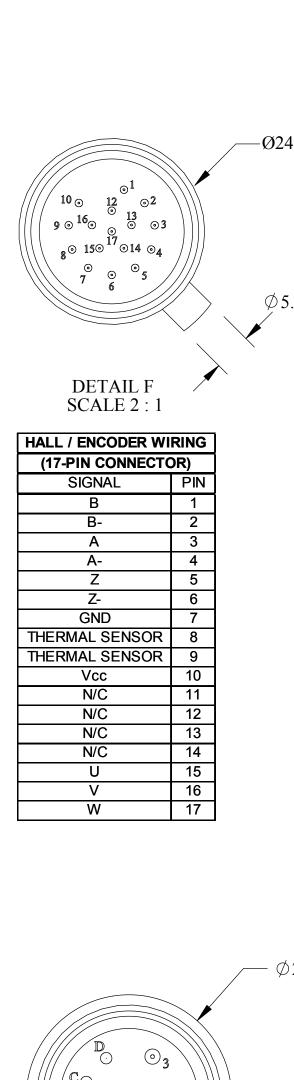
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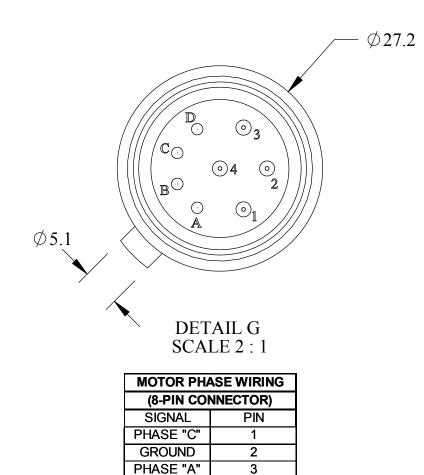
9.6

	TOLERANCES UNL	LESS OTHERWISE SPECIFIED		DANA	HER MOT	TION
	_	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX CORNER BREAK: .005"020"			ULATION OR WITH CON	
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CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90°.	ENGINEER: KDV	CHECKED:		SCALE: 1:1	UNITS: MM	SHEET 9 OF 15



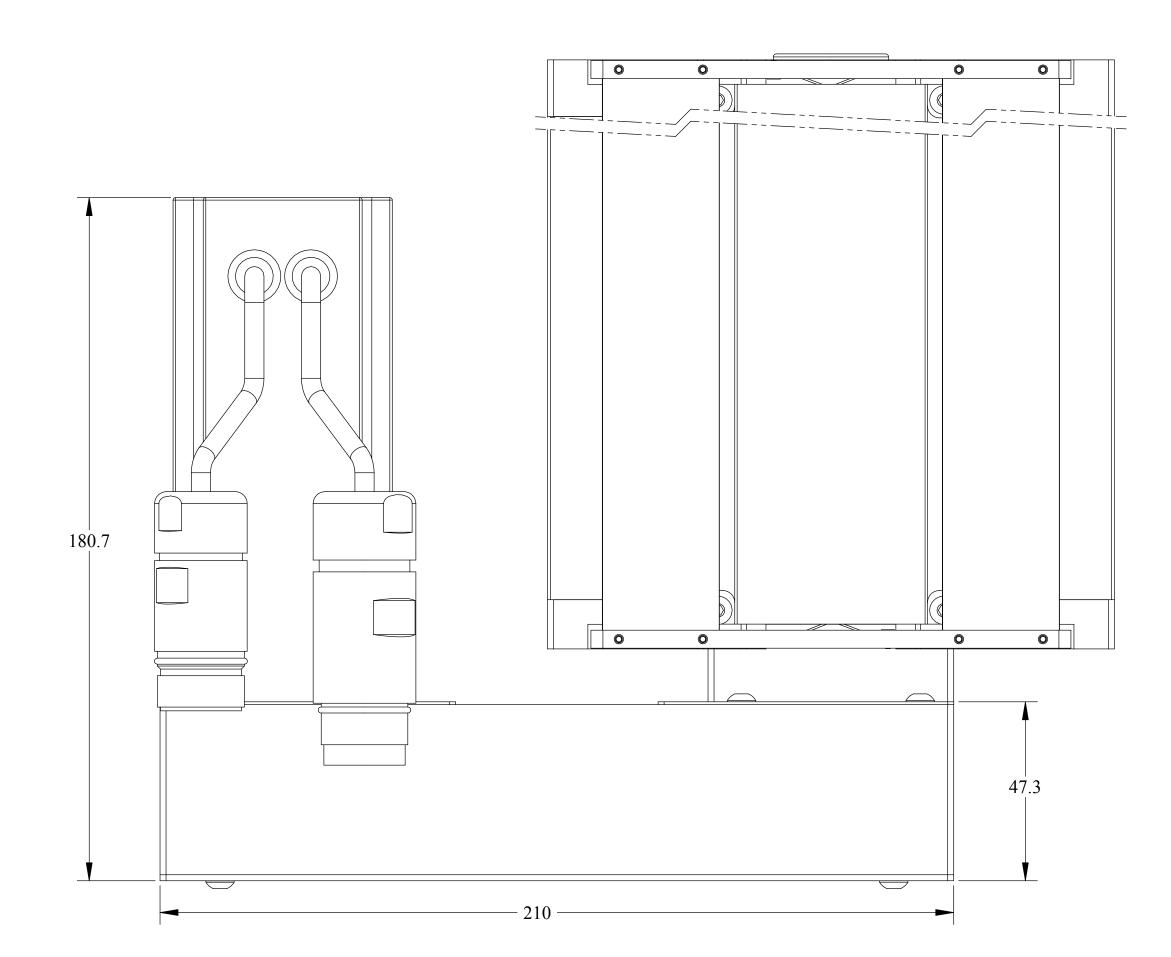


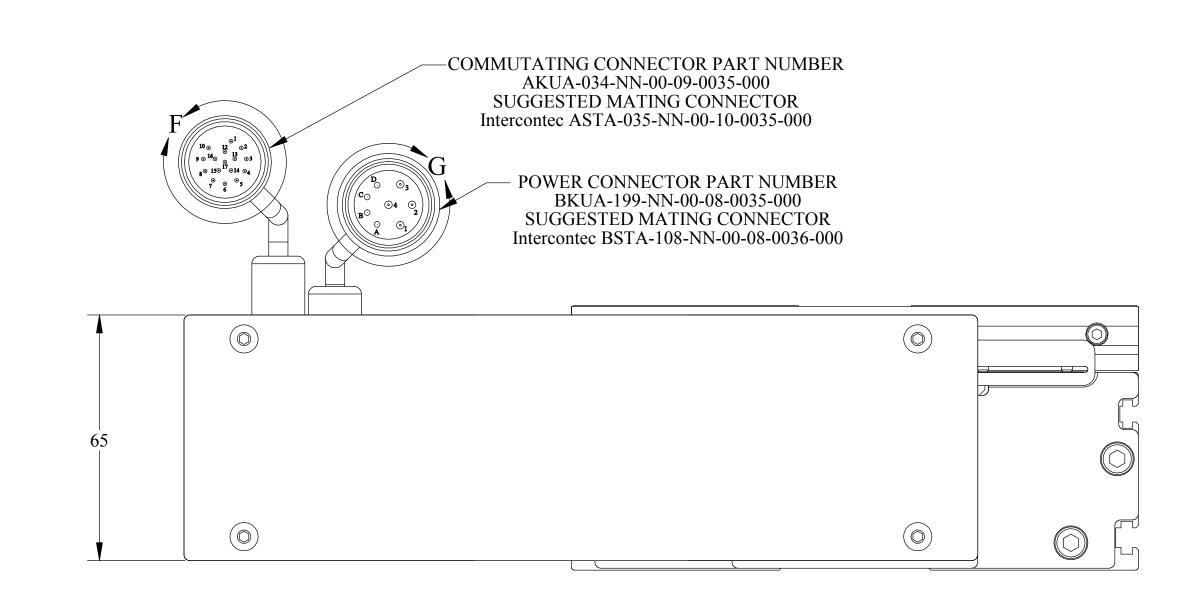




MOTOR PARAMETERS		
Continuous Stall Torque	1.16 N-m	164.3 oz-in
Peak Torque	3.84 N-m	543.8 oz-in
Torque Sensitivity (±10%)	0.52 N-m/A _{RMS}	73.6 oz-in/A _{RM}
Back EMF (±10%)	33.8 V _{RMS} /krpm	
Maximum Speed	8000 rpm	
Weight	1.38 kg	3.04 lb
Rotor Inertia	.22 kgcm ²	1.9x10 ⁻⁴ lb-in-s

PHASE "B" BRAKE +





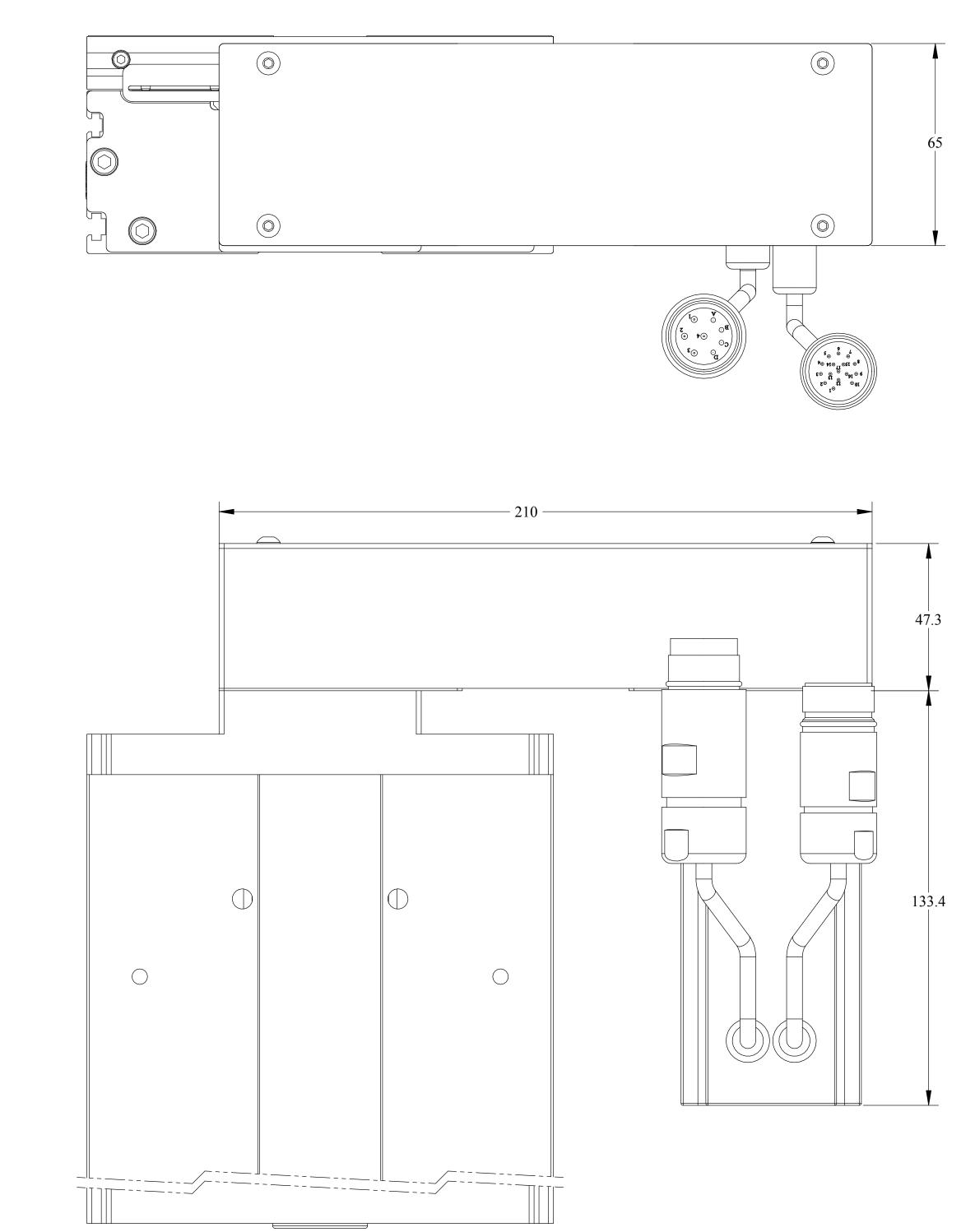
NOTE:
1. BASIC MOTOR DIMENSIONS AND CONNECTOR DIMENSIONS SHOWN
DEEED TO CHEET 2 AND 2 EOD MODE DETAIL C

- REFER TO SHEET 2 AND 3 FOR MORE DETAILS.
- A 8192 CPR ROTARY ENCODER IS INCORPORATED INTO THE SERVOMOTOR.
 1, 3, AND 9 METER CABLES ARE AVAILABLE FOR THIS MOTOR OPTION, AND MUST BE ORDERED SEPERATELY.

THE DOCUMENT IS THE SOLE DRODED TO OF DANIALIED MOTION	FRAC. ± 1/64	CORNER BR
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DRAWN BY: KDV		MATERIAL:	Dwg. No.	41-0140Rev2		SIZE D
ENGINEER: KDV	CHECKED:		SCALE: 1:1	UNITS: MM	SHEET 10	OF 15

BK23 MOTOR - PARALLEL RIGHT WITH CONNECTORS

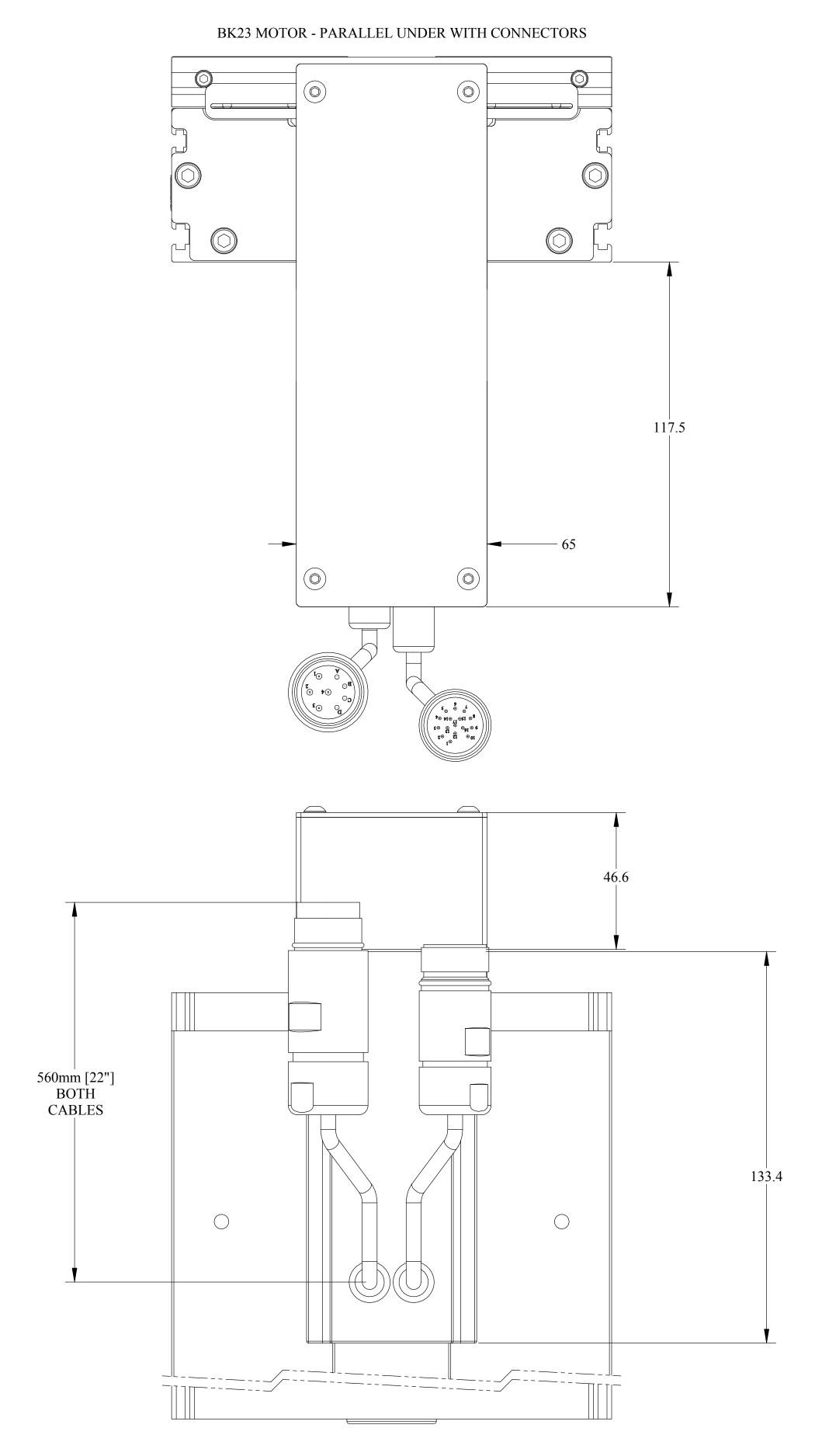


SHEET 11 OF 15

THIRD ANGLE PROJECTION

SCALE: 1:1 UNITS: MM

TOLERANCES UNLESS OTHERWISE SPECIFIED			DANAHER MOTION	
X.XXX ± .01 X.XXX ± .005 X.XXXXX ± .001	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX	FINISH:	DS6 TABULATION BK23 MOTOR, // UNDER, AND RIG	GHT
FRAC. ± 1/64" DRAWN BY: KDV	CORNER BREAK: .005"020" DATE: 12/18/03	MATERIAL:	Dwg. No. 41-0140Rev2	SIZE D

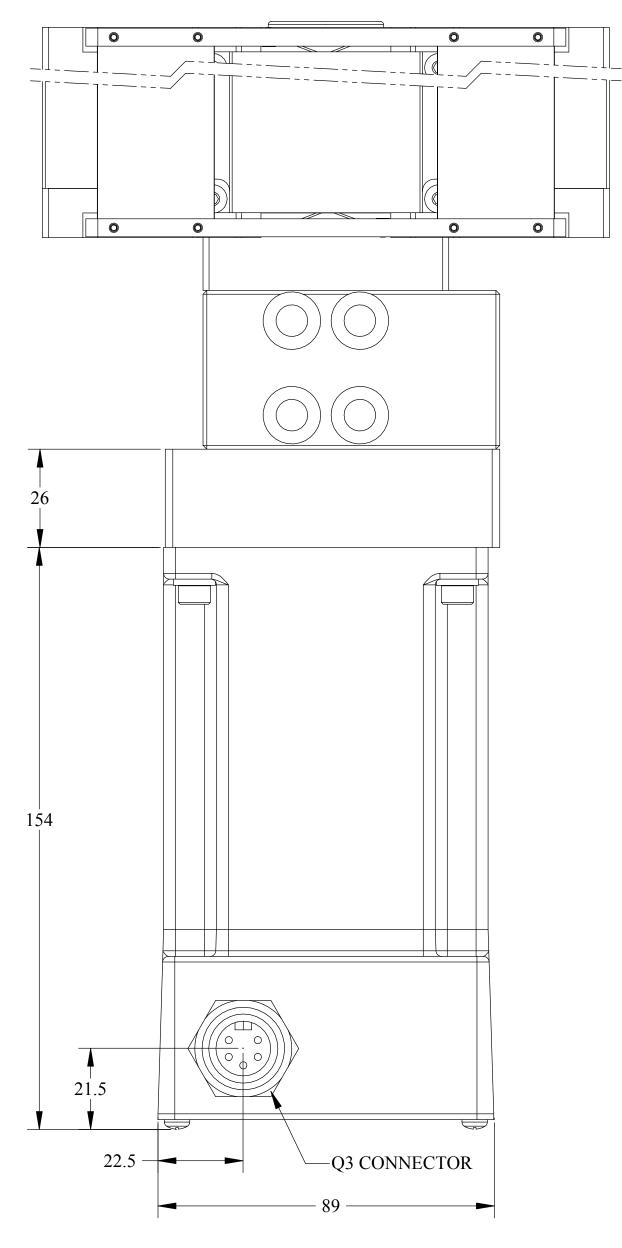


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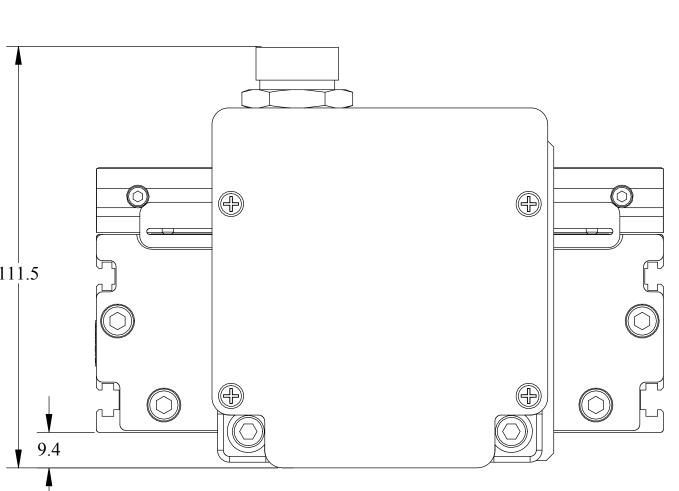
- 1. BASIC MOTOR DIMENSIONS AND CONNECTOR DIMENSIONS SHOWN ON PAGE 10. REFER TO SHEET 2 AND 3 FOR MORE DETAILS.
- A 8192 CPR ROTARY ENCODER IS INCORPORATED INTO THE SERVOMOTOR.
 1, 3, AND 9 METER CABLES ARE AVAILABLE FOR THIS MOTOR OPTION, AND MUST BE ORDERED SEPERATELY.

THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90°. ENGINEER: KDV CHECKED:





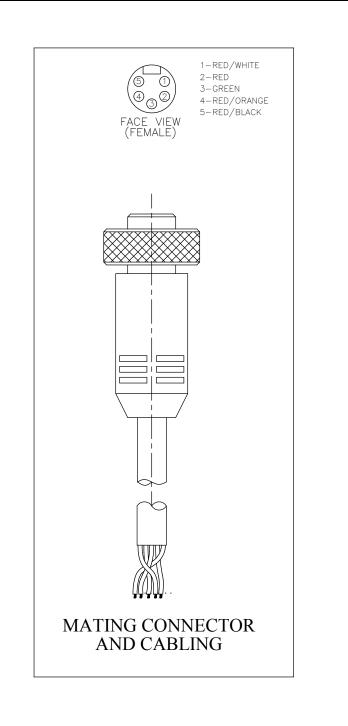
T32 MOTOR - INLINE MOUNT WITH CONNECTOR

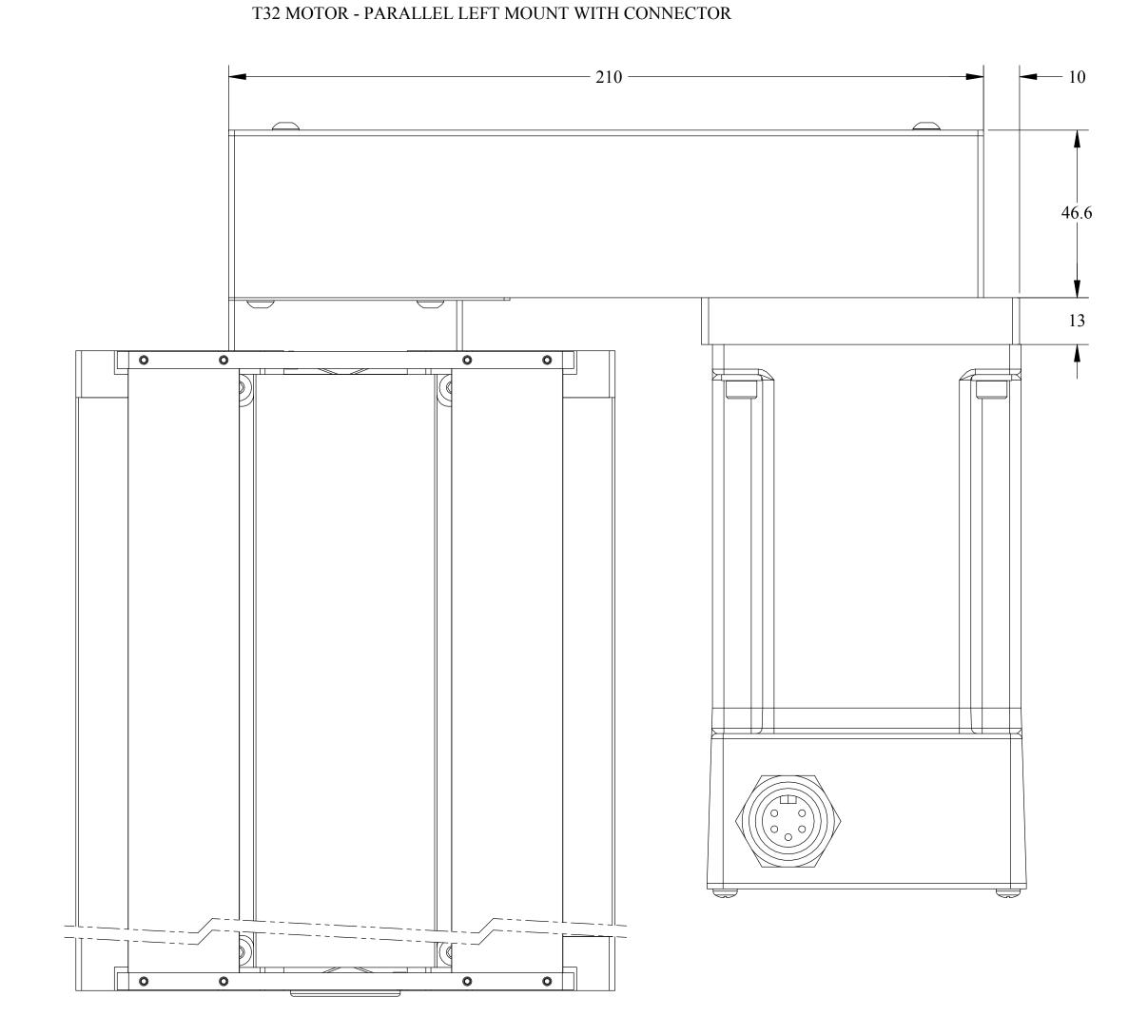


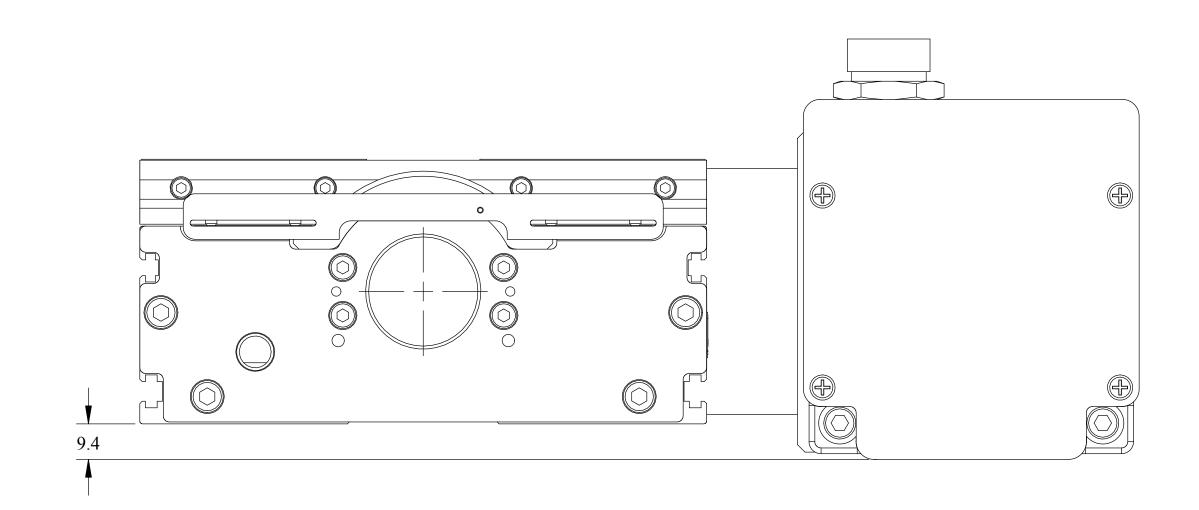
111.5		
9.4		7

111.5		

MOTOR PARAMETERS T32T (Series) T32V (Parallel) Cont. Stall Torque 6.5 N-m [920 oz-in] Rated Cont. Current / Phase 1.60A 3.20A Phase Inductance (±20%) 30mH Weight Rotor Inertia 3.81 kg [8.4lb] 0.268x10⁻³ kg-m² [.038 oz-in-sec²]







FINISH:

SIZE

THIRD ANGLE PROJECTION

NOTE:

- 1.) BASIC MOTOR DIMENSIONS AND CONNECTOR LOCATIONS SHOWN.
- REFER TO SHEETS 2 AND 3 FOR MORE DETAILS

 2.) 3 METER CABLE SUPPLIED WITH MATING CONNECTOR, AS SHOWN.

 8 AND 16 METER CABLES ARE ALSO AVAILABLE.

THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90° ENGINEER: KDV CHECKED:

X.XX ± .01 X.XXX ± .005 X.XXXX ± .001 FRAC. ± 1/64" ALL MACHINED SURFACES FINISH: 63 MAX CORNER BREAK: .005"-.020" MATERIAL: DRAWN BY: KDV DATE: 12/18/03

TOLERANCES UNLESS OTHERWISE SPECIFIED

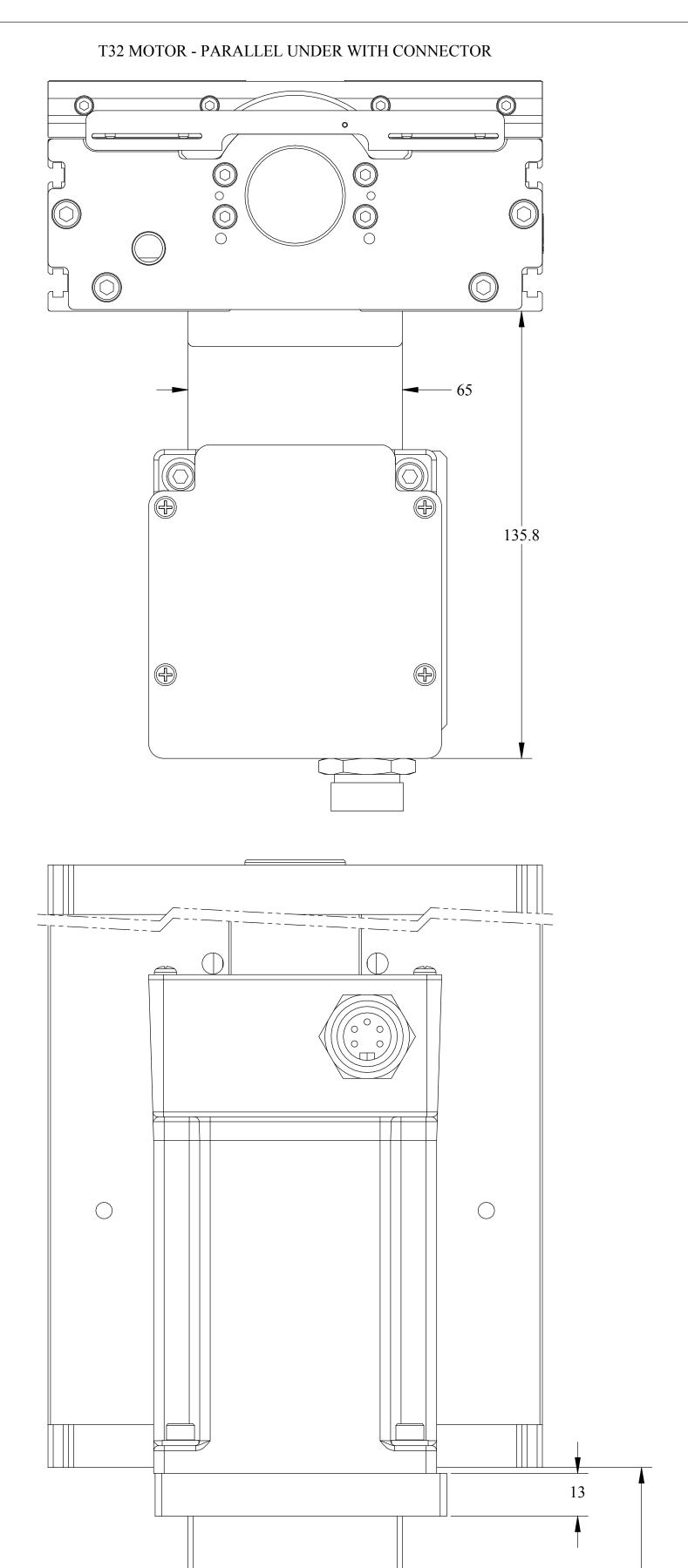
ANGULAR ± 1°

DS6 TABULATION T32 MOTOR INLINE, // LEFT

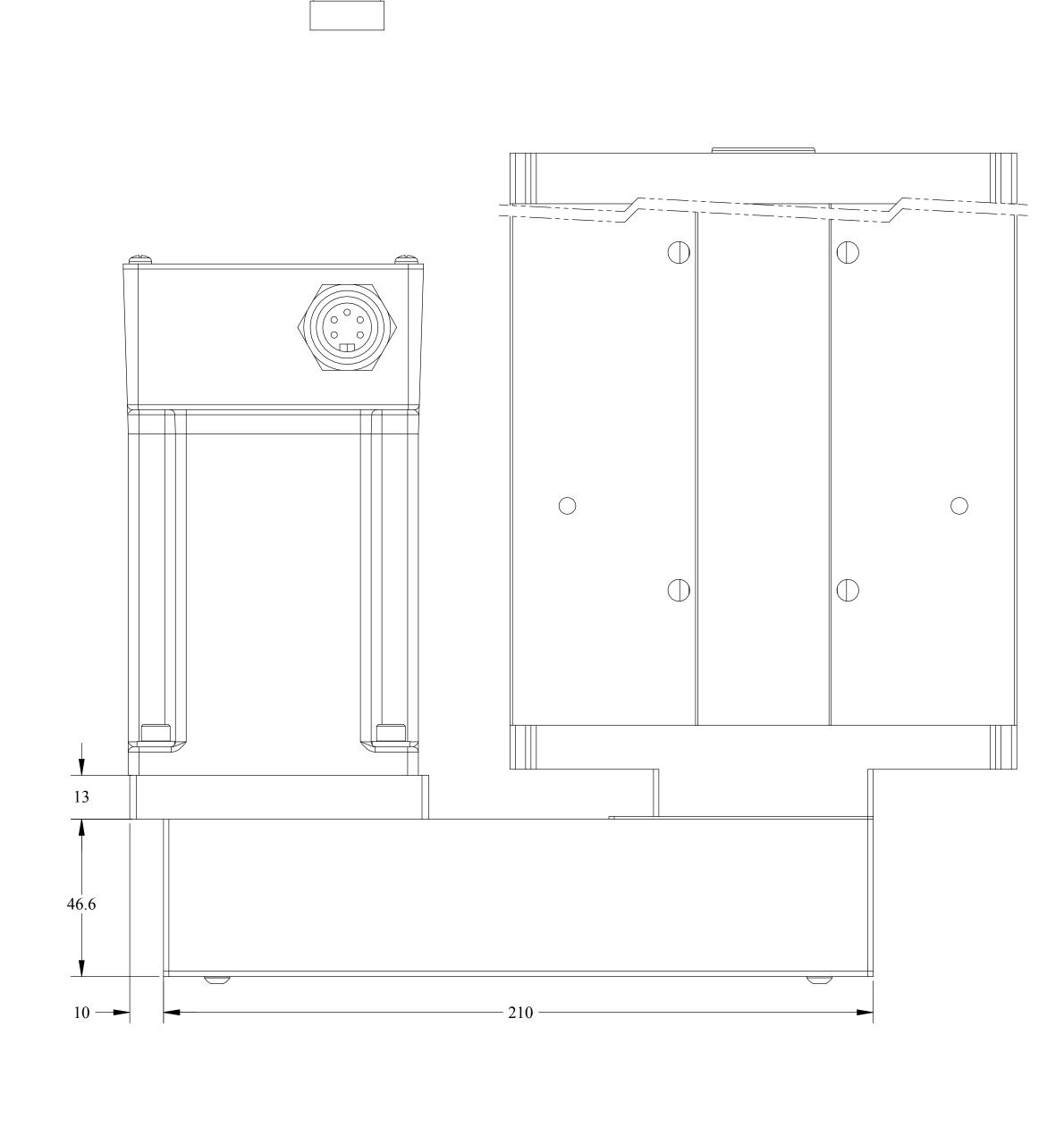
Dwg. No. 41-0140Rev2

DANAHER MOTION

SCALE: 1:1 UNITS: MM SHEET 12 OF 15

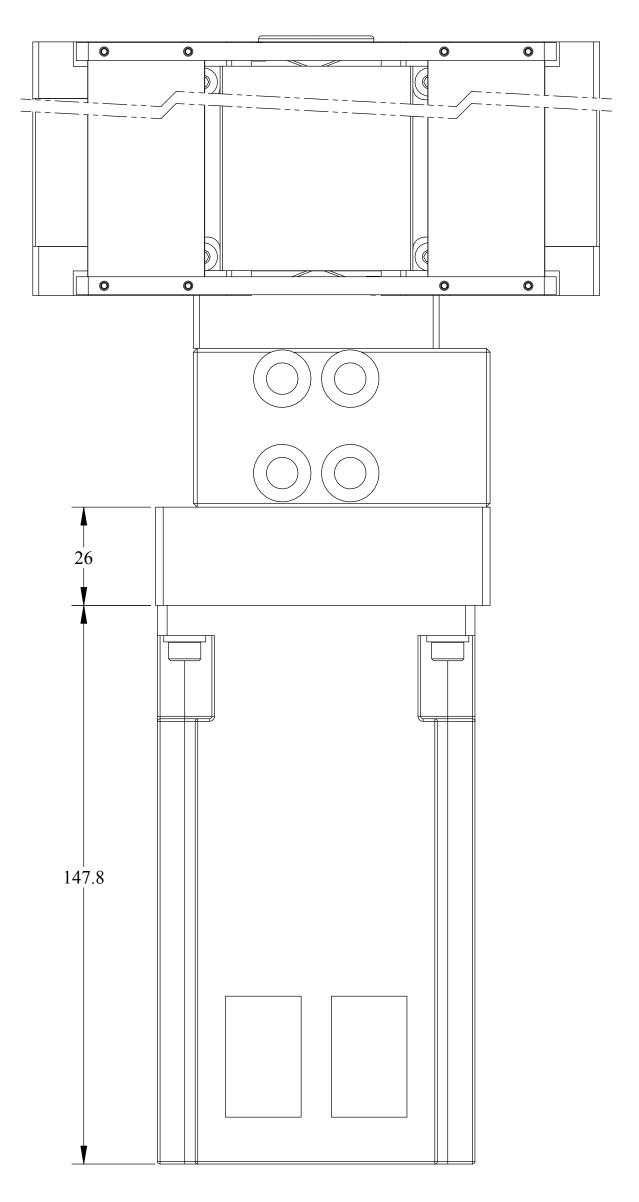


NOTE: 1.) BASIC MOTOR DIMENSIONS AND CONNECTOR LOCATIONS SHOWN. REFER TO SHEETS 2 AND 3 FOR MORE DETAILS

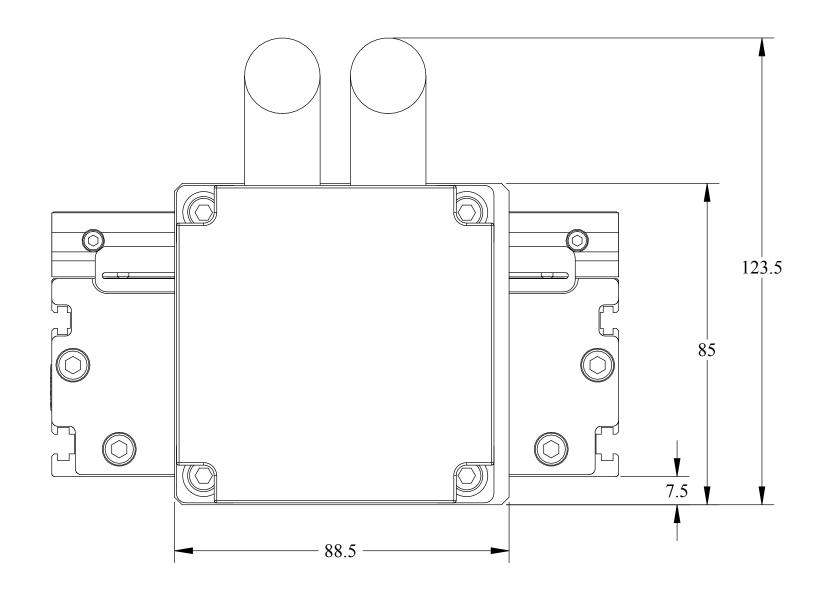


THIRD ANGLE PROJECTION

	TOLERANCES UNLESS OTHERWISE SPECIFIED			DANAHER MOTION		
	X.XX ± .01 X.XXX ± .005 X.XXXX ± .001 FRAC. ± 1/64"	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX CORNER PREAK: 005", 020"		DS6 TABULATION T32 MOTOR, // UNDER, // RIGHT		
THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90°	DRAWN BY: KDV	CORNER BREAK: .005"020" DATE: 12/18/03 CHECKED:	MATERIAL:	Dwg. No. 41-0140Rev2 SIZI SCALE: 1:1 UNITS: MM SHEET 13 OF 15		



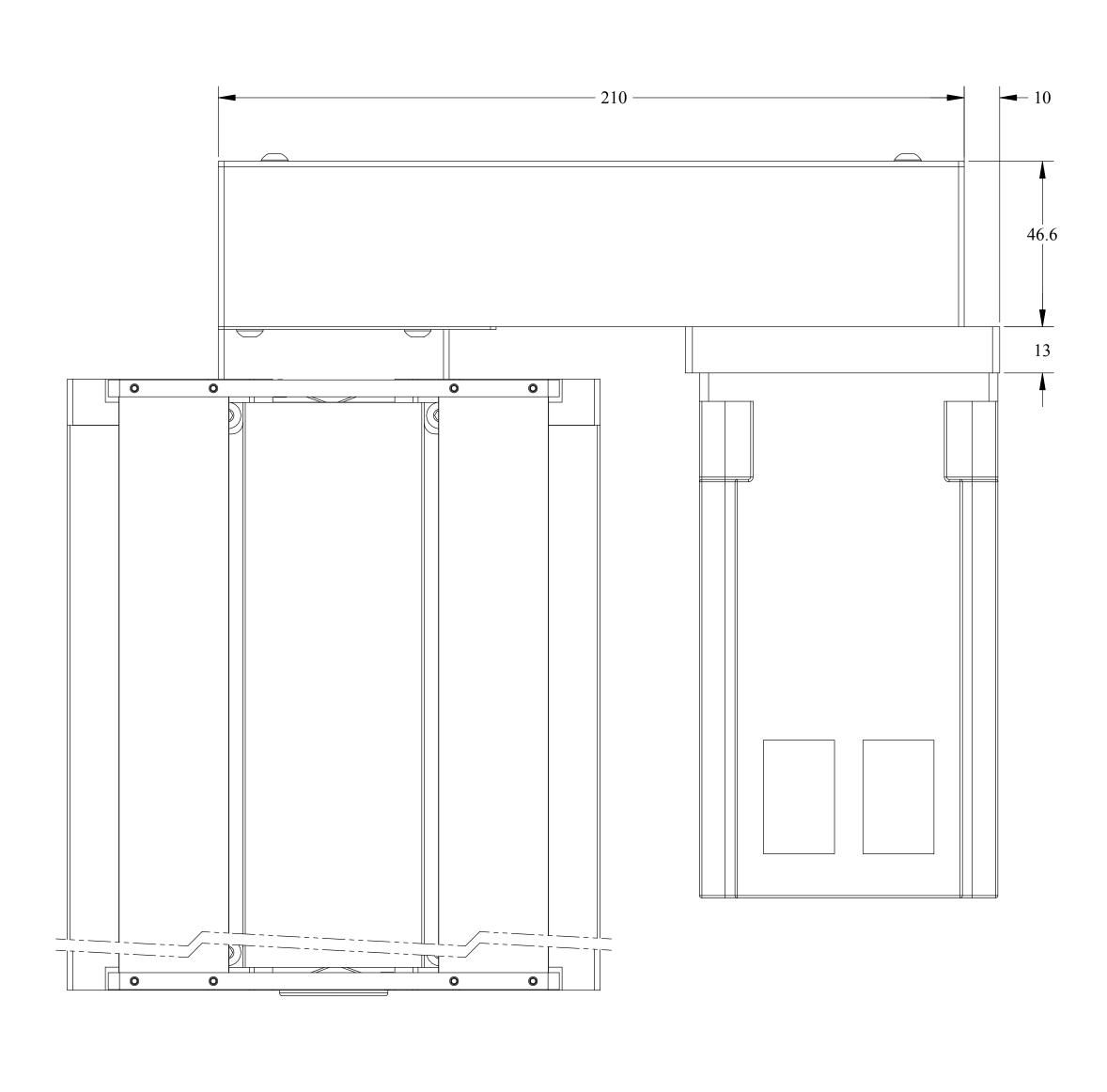
MOTOR PARAMETERS		
Continuous Stall Torque	3.53 N-m	499.89 oz-in
Peak Torque	11.5 N-m	1628.5 oz-in
Torque Sensitivity (±10%)	0.74 N-m/A _{RMS}	6.5 lb-in/A _{RMS}
Back EMF (±10%)	47.5 V _{RMS} /krpm	
Maximum Speed	6000 rpm	
Weight	3.39 kg	7.46 lb
Rotor Inertia	1.5 kgcm ²	.013 lb-in-sec ²

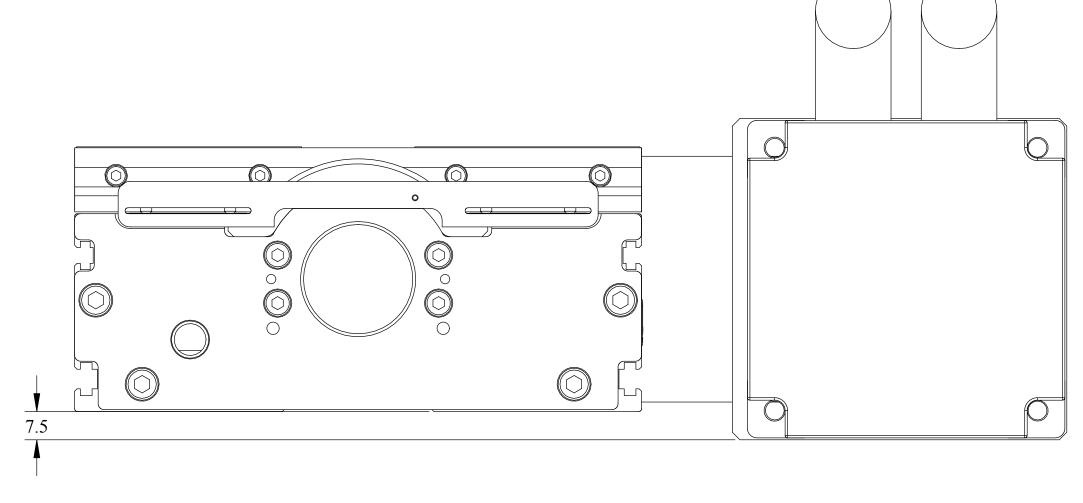


NOTE:

1.) BASIC MOTOR DIMENSIONS AND CONNECTOR LOCATIONS SHOWN. REFER TO SHEET 10 FOR CONNECTOR SIZE AND PINNING.

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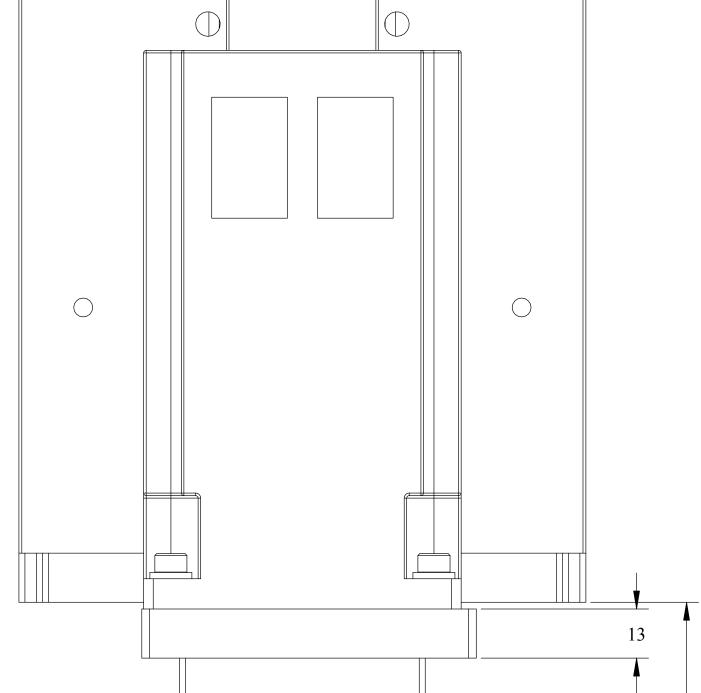


THIRD ANGLE PROJECTION

SCALE: 1:1 UNITS: MM SHEET 14 OF 15

ECO SEE SHEET 1

TOLERANCES UNI	LESS OTHERWISE SPECIFIED		DANAHER MOTION	
X.XX ± .01 X.XXX ± .005 X.XXXX ± .001	ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX	FINISH:	DS6 TABULATION BK32 MOTOR, INLINE // LEFT	
FRAC. ± 1/64"	CORNER BREAK: .005"020"		D No. 41 0140D 2	SIZE
DRAWN BY: KDV	DATE: 12/18/03	MATERIAL:	Dwg. No. 41-0140Rev2	D



NOTE: 1.) BASIC MOTOR DIMENSIONS SHOWN ON PAGE 14. CONNECTOR PINNING AND DIMENSIONS SHOWN ON PAGE 10.

THIS DOCUMENT IS THE SOLE PROPERTY OF DANAHER MOTION AND IS NOT TO BE REPRODUCED OR USED WITHOUT WRITTEN CONSENT. COUNTERSINK TAPPED HOLES TO FULL THREAD DIA. x 90°.

TOLERANCES UNLESS OTHERWISE SPECIFIED DANAHER MOTION X.XX ± .01 X.XXX ± .005 X.XXXX ± .001 FRAC. ± 1/64" ANGULAR ± 1° ALL MACHINED SURFACES FINISH: 63 MAX CORNER BREAK: .005"-.020" FINISH: DS6 TABULATION BK32 MOTOR, // UNDER, // RIGHT Dwg. No. 41-0140Rev2 MATERIAL: DRAWN BY: KDV DATE: 12/18/03 SCALE: 1:1 UNITS: MM SHEET 15 OF 15 ENGINEER: KDV CHECKED:

THIRD ANGLE PROJECTION

SIZE

ECO | SEE SHEET 1