

ETHERCAT Coupler

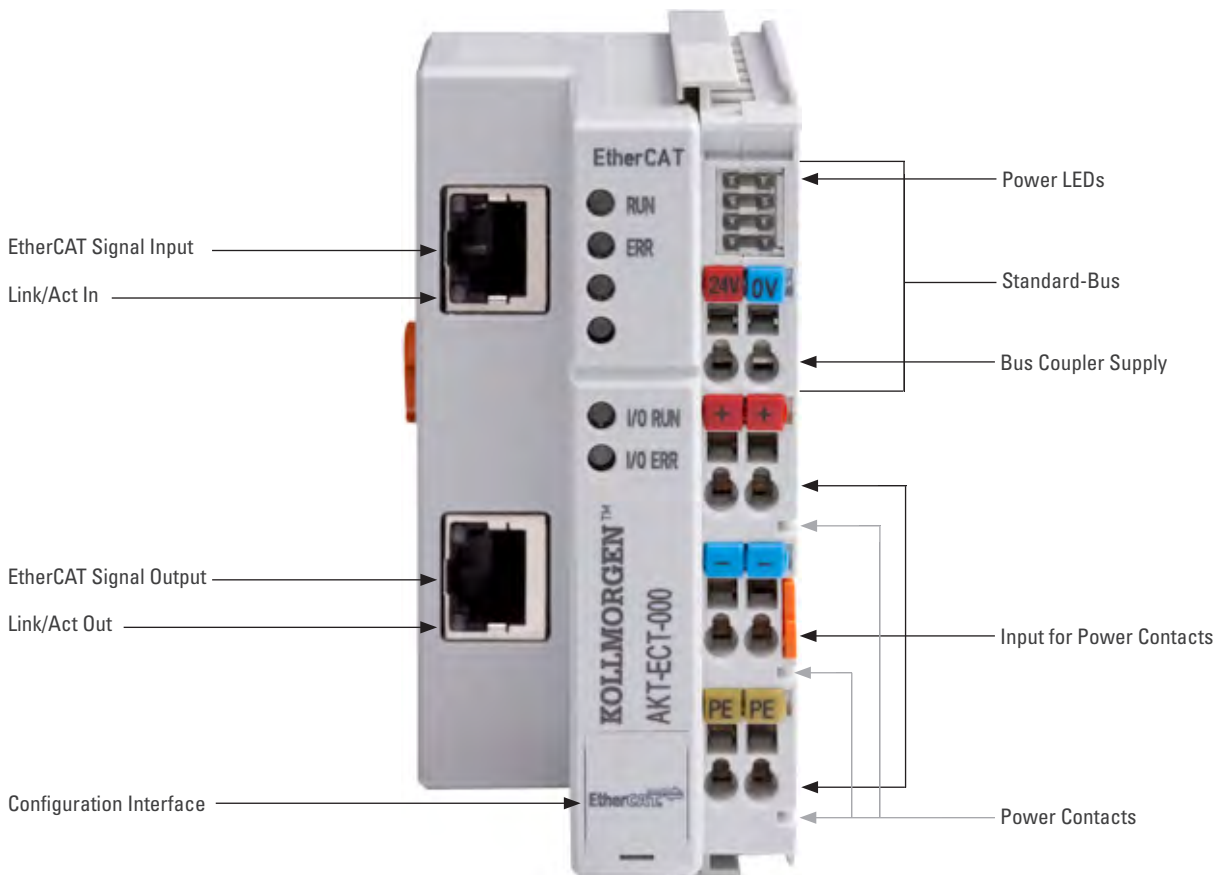
The ETHERCAT Coupler connects EtherCAT, the real-time Ethernet system, with the modular, extendable electronic terminal blocks. A unit consists of a Bus Coupler, a set of terminals, and one end terminal.

The Bus Coupler recognizes the connected Bus Terminals and automatically allocates them into the EtherCAT process image. The Bus Coupler is connected to the network via the upper Ethernet interface. The lower RJ 45 socket may be used to connect further EtherCAT devices in the same strand.

In the EtherCAT network, the ETHERCAT Coupler can be installed anywhere in the Ethernet signal transfer section (100BASE-TX) – except directly at the switch.

EtherCAT (Ethernet Control Automation Technology) is the Ethernet solution for industrial automation, characterized by outstanding performance and particularly simple handling. EtherCAT enables the Ethernet star topology to be replaced with a simple line structure. Optionally, EtherCAT may also be wired in the “classic” way using switches, in order to integrate further Ethernet devices. The master requires no special plug-in card and can be implemented on any existing Ethernet controller using a very simple interface. EtherCAT is therefore also well suited to small and medium control applications, where it will also open up new areas of application for distributed I/Os.

For EtherCAT a separate I/O system in protection class IP 20 is available in the form of EtherCAT Terminals. In contrast to Bus Terminals, where the fieldbus signal is implemented within the Bus Coupler on the internal, fieldbus-independent terminal bus, the EtherCAT protocol remains fully intact down to the individual terminal.



ETHERCAT Coupler

The ETHERCAT Coupler supports the operation of all Bus Terminals. As far as the user is concerned, handling of the analog inputs/outputs is not different to other series. The information is available in the process image of the controller for processing in the form of a byte array.

The analog and multifunctional Bus Terminals can be adapted to each specific application. Depending on the type, the analog Bus Terminals' registers contain temperature ranges, gain values and linearisation characteristics. The Bus Terminals store settings permanently and in a fail-safe manner. Optionally, the Bus Terminals can also be controlled by the control system. Via function blocks (FBs), the programmable logic controller (PLC) or the Programmable Automation Controller (PAC) handles configuration of the complete periphery during the start up phase. If required, the controller can upload the decentralized created configuration data in order to centrally manage and store this data. Therefore, new adjustments are not necessary in the event of replacement of a Bus Terminal. The controller automatically sets the required setting on power up.

Electrical and Mechanical Specification	AKT-ECT-000-000
Number of I/O stations	65,535
Number of I/O points	Depending on controller
Data transfer medium	Ethernet/EtherCAT CAT5 cable
Max. cable length	100 m (100BASE-TX)
Data transfer rates (system data)	100 Mbaud
Data transfer time (system data)	0.01 ms in the case of 10 modules for 32 bit inputs and outputs each (without standard-bus run-time)
Number of Bus Terminals	64 (255 with standard-bus extension)
Max. number of bytes fieldbus	1,024 byte input and 1,024 byte output
Configuration possibility	EtherCAT (ADS)
Data transfer rates	12 Mbaud
Power supply	24 V DC (-15 %/+20 %)
Input current	70 mA + (total standard-bus current)/4, 500 mA max.
Starting current	2.5 x continuous current
Recommended fuse	≤ 10 A
Supply current standard-bus	1750 mA
Power contacts	24 V DC max./10 A max.
Electrical isolation	500 V _{rms} (power contact/supply voltage/Ethernet)
Weight	Approx. 150 g
Operating/storage temperature	0...+55 °C/-25...+85 °C
Relative humidity	95 %, no condensation
Vibration/shock resistance	Conforms to EN 60068-2-6/EN 60068-2-27/29
EMC immunity/emission	Conforms to EN 61000-6-2/EN 61000-6-4
Protect. class/installation pos.	IP 20/variable